

X20IF10A1-1

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1 General information

1.1 Other applicable documents

For additional and supplementary information, see the following documents.

Other applicable documents

| Document name | Title |
|---------------|--------------------------|
| MAX20 | X20 System user's manual |

1.2 Order data

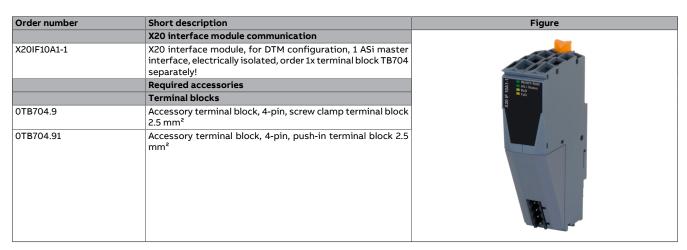


Table 1: X20IF10A1-1 - Order data

1.3 Module description

The interface module is equipped with an ASi master interface. This allows third-party components to be integrated in the B&R system and makes it possible to quickly and easily transfer data in both directions.

Functions:

- ASi master
- Error monitoring

ASi

ASi is a bus system for the lowest field level of automation technology. It allows sensors and actuators to be connected, operated and maintained easily and cost-effectively.

Error monitoring

The status of the module and fieldbus is monitored. An error code is returned if an error occurs.

2 Technical description

2.1 Technical data

| Order number | X20IF10A1-1 |
|--|---|
| Short description | |
| Communication module | ASi interface master |
| General information | |
| B&R ID code | 0xA718 |
| Status indicators | Module status, network status, data transfer |
| Diagnostics | · · · · · · · · · · · · · · · · · · · |
| Module status | Yes, using LED status indicator and software |
| Network status | Yes, using LED status indicator and software |
| Data transfer | Yes, using LED status indicator |
| Fieldbus current consumption | Max. 27 mA |
| Power consumption | |
| Bus | 1.1 W |
| Fieldbus | 0.85 W |
| Additional power dissipation caused by actuators (resistive) [W] | - |
| Certifications | |
| CE | Yes |
| UKCA | Yes |
| ATEX | Zone 2, II 3G Ex nA nC IIA T5 Gc IP20, Ta (see X20 user's manual) FTZÚ 09 ATEX 0083X |
| UL | cULus E115267 Industrial control equipment |
| HazLoc | cCSAus 244665 Process control equipment for hazardous locations Class I, Division 2, Groups ABCD, T5 |
| DNV | Temperature: B (0 to 55°C) Humidity: B (up to 100%) Vibration: B (4 g) EMC: B (bridge and open deck) |
| CCS | Yes |
| LR | ENV1 |
| KR | Yes |
| ABS | Yes |
| BV | EC33B Temperature: 5 - 55°C Vibration: 4 g EMC: Bridge and open deck |
| KC | Yes |
| Interfaces | |
| Interface IF1 | |
| Fieldbus | ASi interface master |
| Type | ASi master profile M4 |
| Variant | 4-pin male multipoint connector |
| Power supply | ASi power supply ¹⁾ |
| Voltage range | 24 to 32 V |
| Controller | netX100 |
| Max. number of slaves | 62 |
| Max. distance | V |
| Standard | 100 m |
| With additional components | 500 m |
| Max. cycle time | 5 ms |
| Response time | Typ. 3 ms |
| Electrical properties | 176.5113 |
| Electrical properties Electrical isolation | PLC isolated from AS (IF1) |
| Operating conditions | 1 Le isolated Hollins (ii 1) |
| Mounting orientation | |
| Horizontal | Yes |
| Vertical | Yes |
| Installation elevation above sea level | 169 |
| 0 to 2000 m | No limitation |
| >2000 m | Reduction of ambient temperature by 0.5°C per 100 m |
| Degree of protection per EN 60529 | IP20 |
| begree or protection per EN 60529 | IPZU |

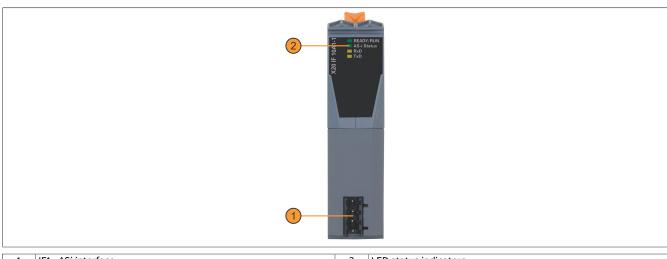
Table 2: X20IF10A1-1 - Technical data

| Order number | X20IF10A1-1 |
|---------------------------------|--|
| Ambient conditions | |
| Temperature | |
| Operation | |
| Horizontal mounting orientation | -25 to 60°C |
| Vertical mounting orientation | -25 to 50°C |
| Derating | - |
| Storage | -40 to 85°C |
| Transport | -40 to 85°C |
| Relative humidity | |
| Operation | 5 to 95%, non-condensing |
| Storage | 5 to 95%, non-condensing |
| Transport | 5 to 95%, non-condensing |
| Mechanical properties | |
| Note | Order 1x terminal block TB704 separately. |
| Slot | In the X20 PLC and expandable bus controller X20BC1083 |

Table 2: X20IF10A1-1 - Technical data

1) An ASi-specified power supply unit is required for the power supply of the AS interface.

2.2 Operating and connection elements



|--|

2.2.1 LED status indicators

| Figure | LED | Color | Status | Description |
|-------------------------------|------------|-----------|------------------|--|
| | READY/RUN | Green/red | Off | No power to module |
| | | Green | On | PCI bus communication in progress |
| READY/RUN AS-i Status RxD TxD | | Red | Blinking | Error when booting |
| | | | On | Communication on the PCI bus has not yet been started |
| | ASi status | Green/red | Off | Configuration not found for this channel |
| | | | Blinking | Configuration mode is active |
| | | Green | Blinking quickly | Communication has stopped |
| | | | Blinking | Configuration error, data exchange is active |
| | | | On | Configuration error-free, data exchange is active |
| | | Red | Blinking | ASi interface power failure |
| | | | On | Fatal system error or hardware error |
| | RxD | Yellow | Flickering or on | The module is receiving data via the ASi interface. |
| | TxD | Yellow | Flickering or on | The module is transmitting data via the ASi interface. |

2.2.2 ASi interface (IF1)

| Interface | | Pinout |
|---|----------|-------------|
| | Terminal | Explanation |
| \ | 1 | ASi+ |
| | 2 | ASi+ |
| ∂ ■ 4 | 3 | ASi- |
| | 4 | ASi- |
| 4-pin male multipoint connector | | |

3 Function description

3.1 The ASi interface

ASi stands for "Actuator Sensor Interface" and is a bus system for the lowest field level of automation technology. Using ASi bus systems provides an easy and affordable way to connect, operate and service sensors and actuators.

ASi is particularly suitable for safety-related components such as safety monitors, emergency stop switches or door locks.

The bus system is composed of a 2-conductor line that transfers both power and information at the same time. This eliminates the need for parallel wiring, where each individual sensor or actuator is connected to the controller's input or output module via a separate line.

ASi is a single master system, which means that only one master can be operated in a network at any one time. The communication between master and slave works via the cyclic polling method. The master sends a poll request to each slave, which is answered by the individual slaves with a poll response.

For additional information, see The ASi interface.

3.2 Error codes

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The module returns an error code if an error occurs. A complete list of all error codes in PDF format is available in under item "Communication_Error" in section "Communication / Fieldbus systems / Support with FDT/DTM / Diagnostic functions / Diagnostics on the runtime system / Master diagnostics" in Automation Help.

4 Commissioning

4.1 Firmware

The module comes with preinstalled firmware. The firmware is part of the Automation Studio project. The module is automatically brought up to this level.

A hardware upgrade must be performed to upgrade the firmware included in Automation Studio (see Help "Project management - Workspace - Upgrades" in Automation Help).

4.2 Operating the module

The interface module can be operated in the slot of a controller or in the slot of an expandable POWERLINK bus controller.

4.2.1 Use in the expandable X20BC1083 POWERLINK bus controller

4.2.1.1 Cyclic data

If this module is connected to the expandable POWERLINK bus controller, the amount of cyclic data is limited by the POWERLINK frame. This is 1488 bytes each in the input and output directions. When using multiple X20IF10xx-1 interfaces or other X2X modules with a POWERLINK bus controller, the 1488 bytes are divided between all connected modules.

4.2.1.2 Operation

It is important to note the following in order to operate the module with the bus controller without problems:

- A minimum revision ≥ E0 is required for the bus controller.
- The module can only be operated with the POWERLINK V2 setting. V1 is not permitted.
- With SDO access to POWERLINK object 0x1011/1 on the bus controller, the firmware and configuration stored on the bus controller are not reset. They can only be overwritten by accessing them again. This affects objects 0x20C0 and 0x20C8, subindexes 92 to 95.

4.2.1.3 Timing characteristics

The internal data transfer results in an additional runtime shift of one cycle per direction.



Information:

For additional information about runtime behavior, see section "Runtime shift" in X20BC1083.

5 The ASi interface

Either 31 or 62 slaves can be operated depending on the type of addressing.

- Standard addressing is suitable for 1 to 32 slaves.
- Extended addressing is suitable for up to 62 slaves. Here, the slaves are grouped as A and B slaves, i.e. 1A to 31A and 1B to 31B).



Information:

Only ASi slaves with the ID code A can be addressed in extended form. With an ID code other than A, only the standard addressing of up to 32 slaves can be used.

5.1 Settings in Automation Studio

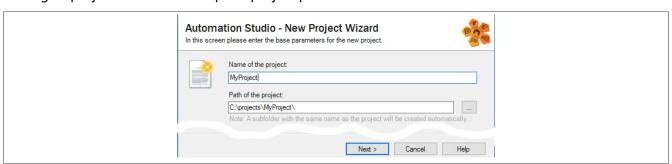
To configure the interface, a new Automation Studio project is created and the suitable settings are made on the module.

5.1.1 Creating an Automation Studio project

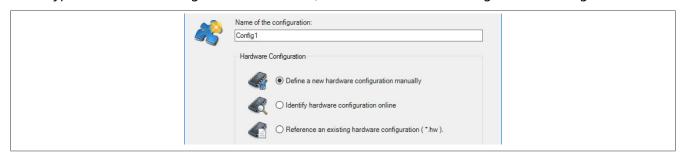
• Create a new Automation Studio project by selecting "New project".



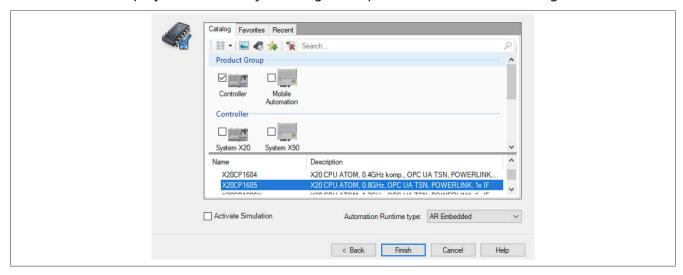
• Assign a project name and set up the project path.



• The type of hardware configuration is selected, and the name of the configuration is assigned.

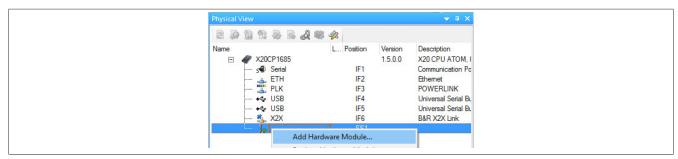


• If "Define a new hardware configuration manually" was selected, the hardware is selected in the next step. In order to simplify the search, different filters can be set for this in the Hardware Catalog. Finally, the Automation Studio project is created by selecting the required hardware is and clicking "Finish".

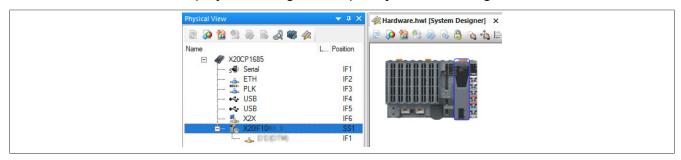


5.1.2 Adding an interface module

• In this example, the interface card is connected in the slot of a controller. Right-clicking on the slot and selecting "Add hardware module" opens the Hardware Catalog.

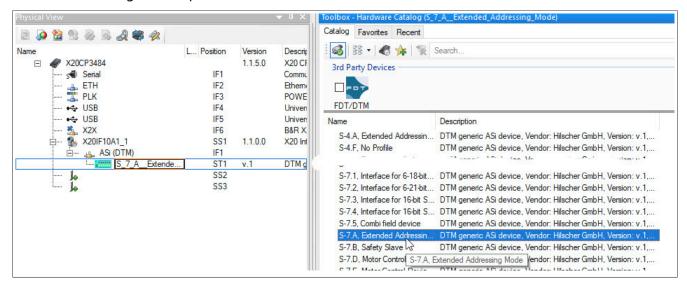


• The module is added to the project via drag-and-drop or by double-clicking on the interface card.



The ASi interface

• ASi slaves from the Hardware Catalog containing the required ASi profile can now be connected to the ASi master via drag-and-drop.

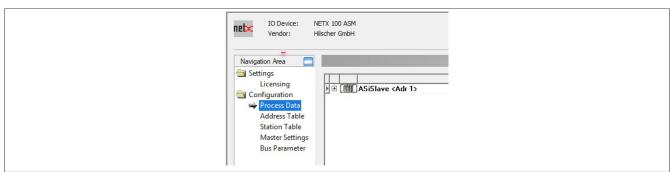


5.1.3 Configuring the ASi master

• Additional module settings can be made under "Device configuration". This configuration environment is opened by right-clicking on the IF interface and selecting "Device configuration".

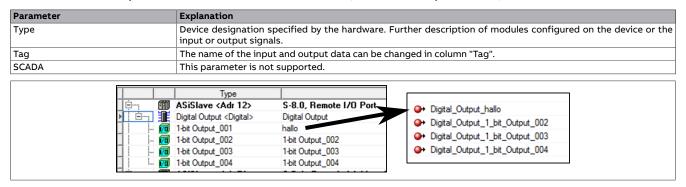


• General settings are made in the device configuration.



Process data

This table lists the process data of all attached slaves (device description files).



Address table

Contains a list of all slaves which are categorized according to their input and output data.

"Display mode" allows toggling between decimal and hexadecimal display.

| Parameter | Explanation |
|-----------------|---|
| Station address | Station address of the assigned slave device. |
| Device | Current device name of the assigned slave |
| Name | Device name of the assigned slave |
| Module | Name of the module |
| Type | Input or output type |
| Length | Number of bytes inserted (IB, QB, IW or QW). |
| Address | Input or output data offset address |

The address table can also be exported as a CSV file.

Station table

All ASi slaves are listed here.

| Parameter | Explanation |
|-----------------|--|
| Activate | This allows the slaves to be enabled or disabled. |
| | Enabled: Process memory is reserved and data is exchanged. |
| | • Disabled: The master reserves memory in the process data image for the slave, but no data is exchanged. |
| Station address | Station address of the slave. Valid addresses: |
| | Standard address range: 1 to 31 |
| | • Extended address range: 1A to 31A and 1B to 31B. In the application, this corresponds to the ranges 1 to 31 and 32 to 62. A/B slaves contain an "A" in their ID code. |
| Device | Name of the assigned slave |
| Name | Name of the assigned slave |
| Vendor | Vendor information |

Master settings

- Start of bus communication

It is possible here to select how data exchange is started on the module.

| Parameter | Explanation |
|----------------------------|---|
| Automatically by device 1) | Data exchange is started automatically after the module is initialized. |
| Controlled by application | Data exchange is started by Automation Runtime. |

 If "Automatically by device" is used, it is possible that the interface module already boots up and establishes a connection to the remote station before the entire system has booted up. If the system requires another restart during startup, however, the interface module will also be restarted.
 Note: In some situations, this may mean that a connection can no longer be established with the remote station.



Information:

"Controlled by application" should preferably be used on the expandable POWERLINK bus controller.

- Module alignment

The addressing mode is defined by the process image here. The addresses (offsets) of the process data are always interpreted as byte addresses.

| Addressing mode | Explanation |
|-------------------|---|
| Byte boundaries | The module address can start on any offset. |
| 2 byte boundaries | The module address can only start on even byte offsets. |



Information:

This configuration is automatically managed by Automation Runtime and is not permitted to be changed (default setting).

- Application monitoring

The module-internal watchdog time can be set here. If the watchdog has been enabled (watchdog time not equal to 0), the hardware watchdog must be reset after the set time at the latest.

| Parameter | Explanation | Values |
|---------------|------------------------------|----------------|
| Watchdog time | Software watchdog disabled | 0 ms |
| | Permissible range of values. | 20 to 65535 ms |
| | Default value: 1000 ms | |



Information:

The watchdog time is reset automatically by Automation Runtime.

- Process image storage format

This is used to define how data is stored in the process image (I/O mapping). The storage format is only applied to data type "Word". This change has no effect on other data types.

| Storage format | Explanation |
|----------------|---|
| Big-endian | MSB/LSB = Higher/Lower byte (Motorola format) |
| Little-endian | MSB/LSB = Higher/Lower byte (Intel format) |



Information:

This configuration is automatically managed by Automation Runtime and is not permitted to be changed (default setting).

- Process data handshake

This parameter configures the handshake for the data exchange between application and device. Only "Buffered, host-controlled" is supported here.

Bus parameters

- Behavior in case of defective slave device

The selection depends on the settings under "Behavior during startup sequence".

- Don't take care about the status of any connected slave devices The slave status is disregarded but the communication remains intact.
- Stop communication if a device is missing Communication is stopped if a slave is missing.
- Stop communication if a device is reporting a periphery failure Communication is stopped if a slave reports a peripheral fault.
- Stop communication if a device is missing or reporting a periphery failure Communication is stopped if a slave is missing or a peripheral fault is reported.

- Behavior during startup sequence

Determines the procedure of the master during startup in correlation with the connected slaves.

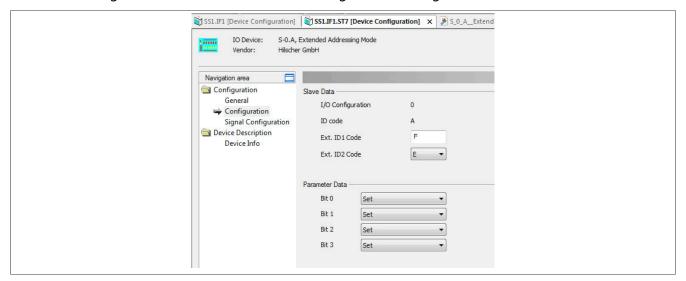
- Protected mode If enabled, the master enters protected data exchange mode. If not enabled, the master enters configuration mode.
- Auto address assignment If enabled, the master assigns a slave the address of a missing slave if it has an identical I/O, ID, ID1 and ID2 code and address 0.

— Overwrite configuration database

This parameter is not supported.

5.1.4 Configuring the ASi slave

• General settings can be made on the ASi slave using "Device configuration.".



General

The description can be adjusted here. However, this is only used by the configuration dialog boxes and not by Automation Studio.

The slave address set on the master is also displayed. See "Station table " on page 11 for setting the address.

Configuration

- Slave data

| Parameter | Explanation |
|-------------------|--|
| I/O configuration | I/O configuration used in the EDS file. This corresponds to the first position of the slave profile. |
| ID code | I/O code used in the EDS file. This corresponds to the second position of the slave profile. |
| Ext. ID1 code | Extended ID code, user-specific |
| Ext. ID2 code | Extended ID code, user-specific |

- Parameter data

| Parameter | Explanation | Values |
|----------------|--|--------|
| Bit 0 to bit 3 | Parameter data to be set by the user. | Set |
| | If these are contained in the EDS file, they are displayed here. | Reset |

Signal configuration

The name and data type of the I/O data point can be adjusted here.

The signal configuration can be set to the default values for the specified slave profile by clicking on "Default".

| Parameter | Explanation |
|-----------|--|
| Modules | Input or output modules of the signal configuration |
| Tag | Editable name of the individual input or output signals. The name can also be changed via the master (see "Process data" on page 10) |
| Data type | Editable data type of the individual input or output signals. The data type can be selected from a list according to the AS slave profile defined in the EDS file. |
| Type | Type of input or output signal |

Device description

General device information can be read here.

5.2 EDS device description file

All possible ASi slave variants have already been imported into Automation Studio as device description files and can be taken from the Hardware Catalog.

Each ASi slave is assigned an ASi profile. The ASi profile is composed of 4 components:

I/O configuration

Contains information about the configuration of individual ASi slave ports: output, input or bidirectional input/output.

• ID code

Contains the ID code of the slave.

Extended ID code 1

Length: 4 bits

In extended address mode, the MSB indicates whether it is an A (MSB = 0) or B (MSB = 1) slave (starting with specification 3.0). In the Automation Studio Hardware Catalog, the extended address mode can be identified by an "A" in the slave address (e. g. "S-0. A"). The lower 3 bits contain additional slave-specific information.

Extended ID code 2

Used for slave-specific settings. See description of the corresponding slave.

5.3 Slave addressing

There are 3 ways to assign an address to an ASi slave.

• With the programming device

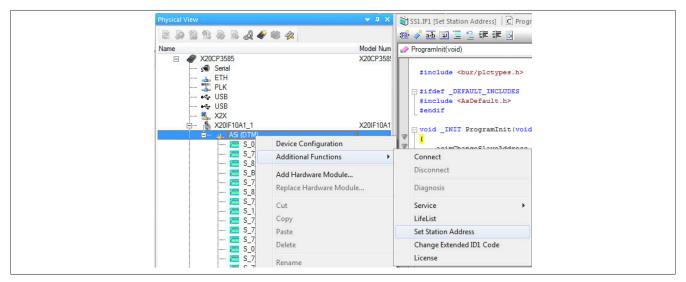
A programming interface is required for this, which does not exist for every slave. If a programming interface is installed in the ASi slave, the slave address can be adjusted via the programming device and the ASi profile can also be read.

• Assignment via function block

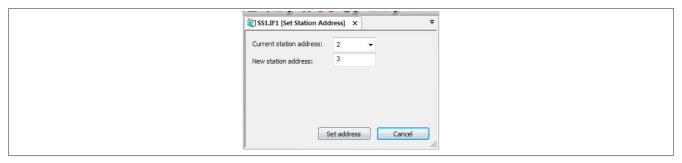
To do this, a program must be created and function block **AsNxAsiM - asimChangeSlaveAddress()** must be programmed. In order to change the slave address using this function block, the current address must be known. In most cases, address 0 (delivery state) is applied to a new ASi slave since no slave is permitted to have address 0.

• Direct mapping via the master

The current slave address is also required here. In the Physical View (Automation Studio), the slave address can be adjusted with a right-click on the ASi interface of the master \rightarrow Additional functions \rightarrow Set station address.



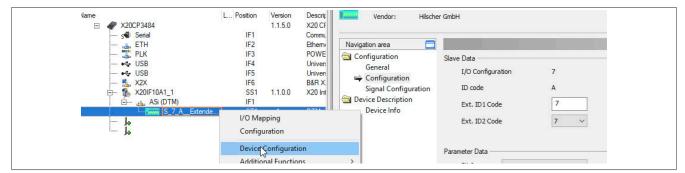
First, the slave to be addressed is selected and the desired new address is specified. A new address can be assigned using "Set address".



5.4 Configuration example

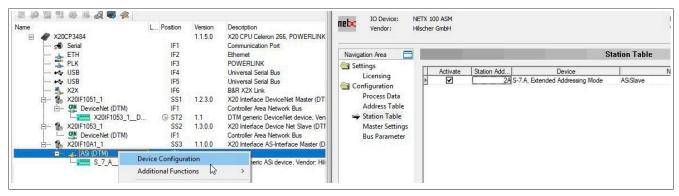
In this example, an ASi slave with the profile S-7.A is configured.

- The desired profile is first selected from the Hardware Catalog and added to the ASi master. See "Adding an interface module" on page 9.
- The ID code settings of the connected device are specified by the ASi slave manufacturer and must be set in the profile. The values under "Ext. ID1 code" and "Ext. ID2 code" are therefore entered via the device configuration of the device description file.



• The address of the ASi slave is then set in the device configuration on the master under "Station table".

The address on the device itself is set differently depending on the ASi slave used, e.g. via a programming device, function block or the master. See "Slave addressing" on page 15.



• Confirm and save all settings with OK. The configuration is transferred to the controller and, if correct, a connection between master and slave is automatically established.

The connection status can be checked with the ModulOK bit in the I/O mapping of the device description file. When ModulOK = True, data can be exchanged between master and slave.

