

X20BR7300

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1 General information

1.1 Other applicable documents

For additional and supplementary information, see the following documents.

Other applicable documents

Document name	Title
MAX20	X20 System user's manual

1.2 Order data

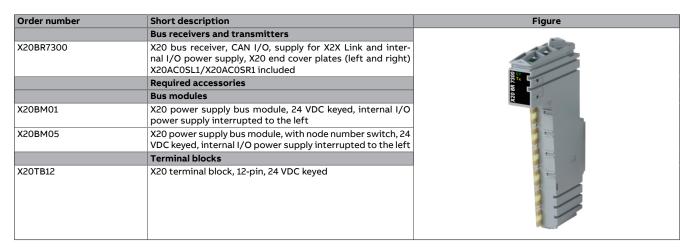


Table 1: X20BR7300 - Order data

1.3 Module description

The bus receiver makes it possible to connect X2X Link I/O nodes to CAN I/O.

Up to 43 logical I/O modules can be connected to the bus receiver. Up to 16 of these can be analog modules.

- · Fieldbus: CAN bus
- · Automatic firmware update via the fieldbus
- Integrated I/O access in B&R Automation Studio

Functions:

- CAN I/O
- Monitoring the operating limits

CAN I/O

CAN I/O is a B&R-specific I/O system that functions via a special protocol on the CAN bus using fixed identifier assignment.

Monitoring operating limits

The voltage of the I/O power supply is monitored for voltage overshoot or undershoot.

2 Technical description

2.1 Technical data

Order number	X20BR7300	
Short description		
Bus receiver	CAN I/O slave	
General information	. , , , , , ,	
B&R ID code	0xEBED	
Status indicators	Module status, bus function, data transfer, I/O power supply, bus power supply	
Diagnostics	riodale status, sus function, data transfer, if o power supply, sus power supply	
Module status	Yes, using LED status indicator	
Bus function	Yes, using LED status indicator	
Data transfer	Yes, using LED status indicator	
Overload	Yes, using LED status indicator Yes, using LED status indicator and software	
	, <u> </u>	
Power consumption for X2X Link power supply Power consumption ¹⁾	1.1 W	
Internal I/O	1.5 W	
Additional power dissipation caused by actuators (resistive) [W]		
Certifications		
CE	Yes	
UKCA	Yes	
ATEX	Zone 2, II 3G Ex nA nC IIA T5 Gc IP20, Ta (see X20 user's manual) FTZÚ 09 ATEX 0083X	
X2X Link and I/O power supply		
Input voltage	24 VDC -15% / +20%	
Fuse	Required line fuse: Max. 10 A slow-blow for wiring Integrated fuse for module, non-replaceable	
Reverse polarity protection	Yes	
X2X Link power supply output		
Nominal output power	2 W	
Parallel connection	No	
Redundant operation	No	
Overload characteristics	Short-circuit proof, temporary overload	
Output I/O power supply		
Nominal output voltage	24 VDC	
Behavior on short circuit	Required line fuse	
Permissible contact load	10 A	
Interfaces		
Fieldbus	CAN I/O slave	
Variant	Connection via 12-pin terminal block X20TB12	
Max. distance	1000 m	
Transfer rate	Max. 1 Mbit/s	
Default transfer rate	Automatic transfer rate detection	
X2X Link cycle time	Permanently set to 1 ms ²⁾	
Synchronization between bus systems possible	No	
Electrical properties	NO	
Electrical isolation	X2X Link supply not isolated from X2X Link power supply I/O supply not isolated from I/O power supply CAN I/O not isolated from I/O or X2X Link power supply	
Operating conditions		
Mounting orientation		
Horizontal	Yes	
Vertical	Yes	
Installation elevation above sea level		
0 to 2000 m	No limitation	
>2000 m	Reduction of ambient temperature by 0.5°C per 100 m	
Degree of protection per EN 60529	IP20	
Ambient conditions		
Temperature		
Operation		
Operation	-25 to 60°C	
Operation Horizontal mounting orientation		
Operation Horizontal mounting orientation Vertical mounting orientation	-25 to 60°C -25 to 50°C	
Operation Horizontal mounting orientation		

Table 2: X20BR7300 - Technical data

Order number	X20BR7300	
Relative humidity		
Operation	5 to 95%, non-condensing	
Storage	5 to 95%, non-condensing	
Transport	5 to 95%, non-condensing	
Mechanical properties		
Note	Order 1x terminal block X20TB12 separately.	
	Order 1x power supply bus module X20BM01 separately, X20 end	
	cover plates (left and right) X20AC0SL1/X20AC0SR1 included	
Pitch	12.5*0.2 mm	

Table 2: X20BR7300 - Technical data

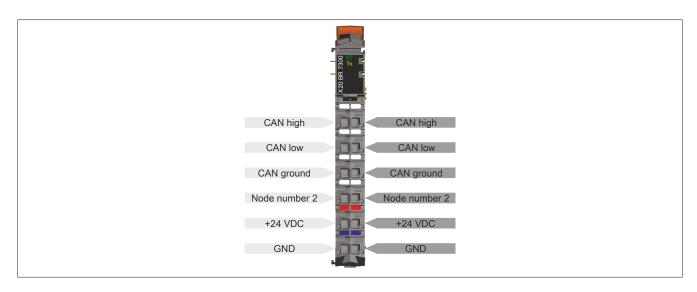
- 1) The specified values are maximum values. For examples of the exact calculation, see section "Mechanical and electrical configuration" in the X20 system user's manual.
- 2) CAN I/O data points are processed in Automation Runtime in a separate cycle set to 10 ms (CAN I/O cycle).

2.2 LED status indicators

Figure	LED	Color	Status	Description		
	ST ¹⁾	Green	Off	No power supply		
			Double flash	Mode BOOT (during firmware update) ²⁾		
			Blinking	Mode PREOPERATIONAL		
T			On	Mode RUN		
- AT		Red	Double flash	The LED indicates one of the following states:		
OST E	The X2X Link power supply of the power supply is overlo		The X2X Link power supply of the power supply is overloaded.			
2				The input voltage for the X2X Link power supply is too low.		
X20 BR			On	CAN connection reports BusOff status		
(20		Green/Red	Flickering	Transfer rate detection in progress		
			Blinking	I/O power supply too low		
		Blinking green Single red flas		PREOPERATIONAL mode: CAN connection reports warning limit reached		
		Steady green flash		RUN mode: CAN connection reports warning limit reached		
	Tx	Yellow	Off	Bus receiver not transmitting any data via CAN I/O fieldbus		
			On	Bus controller transmitting data via the CAN I/O fieldbus		

- 1) LED "ST" is a green/red dual LED.
- 2) Depending on the configuration, a firmware update can take up to several minutes.

2.3 Pinout



2.4 Setting the module's node number

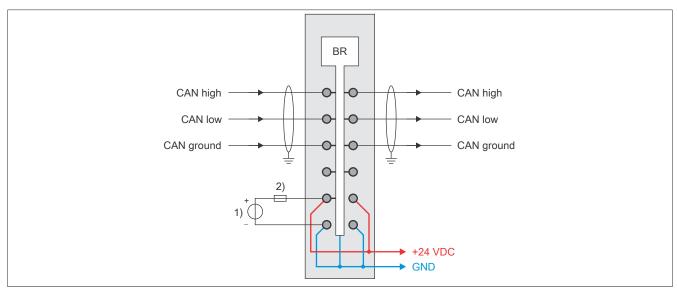
Node number 1 or 2 can be set on the module. By default, the module is set to node number 1. Node number 2 is set on the module by connecting terminal connections 14 and 24 using a jumper (see also "Connection examples", "Example 2: Node number 2" on page 6).

2.5 Terminating resistor

CAN networks are cabled using a bus structure where both ends of the bus must be wired with a terminating resistor. The terminating resistor must be wired externally (see also "Connection examples", "Example 3: With terminating resistor" on page 7).

2.6 Connection examples

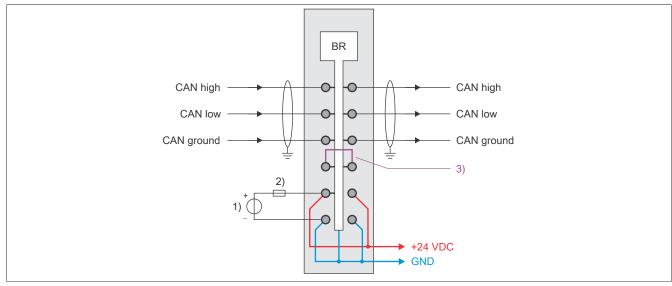
Example 1



- 1) Supply for the X2X Link and I/O power supply
- 2) Fuse, 10 A slow-blow

Example 2: Node number 2

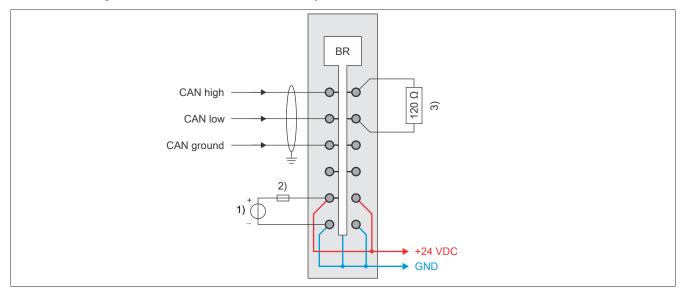
By default, the module is set to node number 1. The module is set to node number 2 if terminal connection 14 is connected to 24 using a jumper.



- 1) Supply for the X2X Link and I/O power supply
- 2) Fuse, 10 A slow-blow
- Setting node number 2 using a jumper

Example 3: With terminating resistor

The terminating resistor must be wired externally.



- 1) Supply for the X2X Link and I/O power supply
- 2) Fuse, 10 A slow-blow
- 3) Terminating resistor

2.7 Automatic transfer rate detection

After startup, the bus receiver goes into "Listen only" mode. This means the bus receiver behaves passively on the bus and only listens.

The bus receiver attempts to receive valid objects. If receive errors occur, the bus receiver switches to the next transfer rate in the lookup table.

If no objects are received, all transfer rates are tested cyclically. This procedure is repeated until valid objects are received.

Starting transfer rate

The bus receiver begins the search with this transfer rate. The last detected transfer rate is used after a software reset (command code 20).

Lookup table

The bus receiver tests the transfer rate according to this table. Beginning with the starting transfer rate, the controller switches to the next lower transfer rate. At the end of the table, the bus receiver restarts the search from the beginning.

Transfer rate Transfer rate
1000 kbit/s
500 kbit/s
250 kbit/s
125 kbit/s
50 kbit/s
20 kbit/s
10 kbit/s

2.8 Logical I/O modules

Up to 43 I/O modules can be connected to the bus receiver (up to 16 of these can be analog modules). This value refers not to the physical but the logical I/O module slots.



Information:

Physical I/O modules can take up more than one digital or analog slot.

The following table lists all CAN I/O-capable X20 modules and how many logical digital or analog slots they occupy.

Analog module slots 1 1 1 1 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1
1 1 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
1 1 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1
1 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
2 1 1 1 1 1 1 1
1 1 1 1 1 1 1
1 1 1 1 1 1 1
1 1 1 1
1 1 1 1
1 1 1
1 1
1
1
1
2
2
2
4
1
2
1
1
1
1
1
3
1
1
1
1
1
2
1
1
Firmware version ≤1.1.3.0: 1 Firmware version >1.1.3.0: 2
2
1
1
1
8
1
1
2
1
1
1
4
1
4
3
1
1
1
1
2
1
1
1
1

Marabala.	Divited and desired	Auglau aandala alaka
Module	Digital module slots	Analog module slots
X20DC1198	0	1
X20DC11A6	0	1
X20DC1376	0	1
X20DC137A	0	1
X20DC1396	0	1
X20DC1976	0	1
X20DC2190	0	4
X20DC2395	0	1
X20DC2396	0	1
X20DC2398	0	2
X20DC4395	0	2
X20DI0471	2	0
X20DI2371	1	0
X20DI2372	1	0
X20DI2377	0	1
X20DI4371	1	0
X20DI4372	1	0
X20DI4375	1	0
X20DI4653	1	0
X20DI4760	1	0
X20DI6371	1	0
X20DI6372	1	0
X20DI6373	1	0
X20DI6553	1	0
X20DI8371	1	0
X20DI9371	2	0
X20DI9371 X20DI9372	2	0
X20DID371	1	0
X20DIF371	2	0
X20DIF372	2	0
X20DM9324	1	0
X20DMF320	0	2
X20DO2321	1	0
X20DO2322	1	0
X20D02623	0	1
	0	1
X20DO2633		
X20DO2649	1	0
X20DO4321	1	0
X20DO4322	1	0
X20DO4332	1	0
X20DO4332-1	0	1
X20DO4529	1	0
X20DO4613	0	1
X20D04623	0	1
X20DO4633	0	1
X20DO4649	1	0
X20DO4F49	1	0
X20DO6321	1	0
X20DO6322	1	0
X20DO6325	1	0
X20DO6529	1	0
X20D06639	1	0
X20D08232	1	0
X20D08322	1	0
X20D08331	1	0
X20DO8332(-1)	1	0
X20DO9321	2	0
X20DO9322	2	0
X20DOD322	1	0
X20D0F321	2	0
X20D0F322	2	0
X20D0F322 X20DS1828	0	2
X20DS1928	0	2
X20DS438A	0	3
X20MM2436	0	1
X20MM3332	0	1
X20MM4331	0	2
X20MM4455	0	4
X20MM4456	0	4
X20PD0011	1	0
X20PD0012	1	0
X20PD0016	1	0
X20PD0053	0	1
X20PD2113	1	0

Technical description

Module	Digital module slots	Analog module slots
X20PS2100	0	1
X20PS2110	0	1
X20PS3300	0	1
X20PS3310	0	1
X20PS4951	1	0
X20PS9400	0	1
X20PS9402	0	1
X20SM1426	0	1
X20SM1436	0	1
X20SM1436-1	0	1
X20SM1444-1	0	2
X20SM1446-1	0	2

3 Function description

3.1 CAN I/O

CAN I/O is a B&R-specific I/O system that functions via a special protocol on the CAN bus using fixed identifier assignment.

3.2 Monitoring the operating limits

The status of the bus supply voltage and the bus current can be read out.

Bit	Description
0	No error
1	Warning for overcurrent (>0.4 A) or undervoltage (<4.7 V)

The status of the I/O supply voltage can be read out.

Bit	Description	
0	I/O power supply above the warning limits of (20.4 V)	
1 I/O power supply below the warning limits (20.4 V)		



Information:

The register is described in "Status of the module" on page 13.

4 Commissioning



Information:

Modules after a gap in X2X Link station numbers are not configured by the bus receiver. This gap is caused by unconnected X20 modules.



Information:

Dummy modules and bus modules with integrated node number switch are not supported by the bus receiver.



Information:

With multifunction modules, the bus receiver supports only the default function model in the event of automatic configuration by the bus receiver (see the respective module description).



Information:

To be able to use the bus receiver in general, a hardware upgrade ≥2.0.0.0 is also required for bus module X20BM01.

The hardware upgrade is only permitted to be installed in the following versions of Automation Studio!

- Automation Studio 4.2.7.54 to 4.2.x.x
- Automation Studio ≥4.3.2.103
- Automation Runtime ≥4.26

A hardware upgrade ≥2.0.0.0 of bus module X20BM01 for Automation Studio versions <4.2.7.54 and Automation Studio versions from 4.3.1.0 to 4.3.2.102 results in error behavior of bus module X20BM01.

Unconfigured X20 modules

Unconfigured X20 modules that are connected to the bus receiver have a special blinking behavior of LED "r" or "S".

The green LED blinks with a single or double flash. This blinking behavior depends on the respective X20 module.



Information:

In this case, the double flash does not indicate a firmware update, but a missing configuration.

4.1 SG4

The module comes with preinstalled firmware. The firmware is also part of the Automation Runtime operating system for the PLC. With different versions, the Automation Runtime firmware is loaded onto the module.

Current firmware is made available automatically by updating Automation Runtime.

5 Register description

5.1 General data points

In addition to the registers described in the register description, the module has additional general data points. These are not module-specific but contain general information such as serial number and hardware variant.

General data points are described in section "Additional information - General data points" in the X20 System user's manual.

5.2 Overview of registers

Register	Name	Data type	Read Write		rite	
			Cyclic	Acyclic	Cyclic	Acyclic
0	Status of the module	USINT	•			
	IF1.ST1.StatusInput01	Bit O				
	IF1.ST1.StatusInput02	Bit 1				

5.3 Status of the module

Name:

IF1.ST1.StatusInput01 and IF1.ST1.StatusInput02

The following voltage and current states of the module are monitored in this register:

- X2X Link supply current >0.4 A is indicated as a warning.
- X2X Link supply voltage <4.7 V is indicated as a warning.
- 24 VDC I/O supply voltage <20.4 V is indicated as a warning.

Data type	Values
USINT	See the bit structure.

Bit structure:

Bit	Description	Value	Information
0	IF1.ST1.StatusInput01	0	No error
	X2X Link supply current and X2X Link supply voltage	1	Warning in the event of overcurrent (>0.4 A) or undervoltage (<4.7 V)
1	IF1.ST1.StatusInput02 I/O supply voltage	0	I/O supply voltage greater than or equal to the warning level of 20.4 V
		1	I/O supply voltage less than the warning level of 20.4 V
2 - x	Reserved	0	