

# X20AO4635

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#### **Publishing information**

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## 1 General information

### 1.1 Other applicable documents

For additional and supplementary information, see the following documents.

### Other applicable documents

Document name	Title
MAX20	X20 System user's manual

### 1.2 Order data

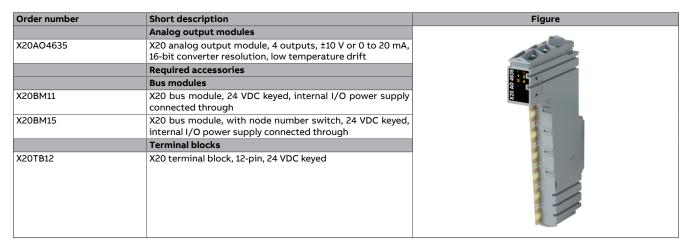


Table 1: X20AO4635 - Order data

### 1.3 Module description

The module is equipped with 4 outputs with 16-bit, including sign, digital converter resolution. The module has only a low temperature drift. It is possible to select between the current and voltage signal using different terminals.

#### **Functions:**

· Analog outputs

### **Analog outputs**

The module is equipped with analog outputs with a configurable current and/or voltage signal.

# 2 Technical description

### 2.1 Technical data

Order number	X20AO4635
Short description	
I/O module	4 analog outputs ±10 V or 0 to 20 mA, low temperature drift
General information	
B&R ID code	0xA7FE
Status indicators	I/O function per channel, operating state, module status
Diagnostics	
Module run/error	Yes, using LED status indicator and software
Channel type	Yes, using software
Power consumption	
Bus	0.01 W
Internal I/O	1.5 W
Additional power dissipation caused by actua-	
tors (resistive) [W]	
Certifications	
CE	Yes
UKCA	Yes
ATEX	Zone 2, II 3G Ex nA nC IIA T5 Gc
	IP20, Ta (see X20 user's manual) FTZÚ 09 ATEX 0083X
UL	cULus E115267
	Industrial control equipment
HazLoc	cCSAus 244665
	Process control equipment
	for hazardous locations
DANY	Class I, Division 2, Groups ABCD, T5
DNV	Temperature: <b>B</b> (0 to 55°C) Humidity: <b>B</b> (up to 100%)
	Vibration: <b>B</b> (4 g)
	EMC: <b>B</b> (bridge and open deck)
CCS	Yes
LR	ENV1
KR	Yes
ABS	Yes
BV	EC33B
	Temperature: 5 - 55°C
	Vibration: 4 g
	EMC: Bridge and open deck
KC	Yes
Analog outputs	
Output	±10 V or 0 to 20 mA, via different terminal connections
Digital converter resolution	
Voltage	±15-bit
Current	15-bit
Conversion time	50 μs for all outputs
Cattling times an autout about a surprise	
Settling time on output change over entire	500 μs
range	·
range Switch on/off behavior	500 µs Internal enable relay for startup
range Switch on/off behavior Max. error <sup>1)</sup>	Internal enable relay for startup
range Switch on/off behavior Max. error <sup>1)</sup> Gain	Internal enable relay for startup  ±0.04% <sup>2)</sup>
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset	±0.04% <sup>2)</sup> ±0.022% <sup>3)</sup>
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection	Internal enable relay for startup  ±0.04% <sup>2)</sup>
range Switch on/off behavior Max. error <sup>1)</sup> Gain Offset	±0.04% <sup>2)</sup> ±0.022% <sup>3)</sup>
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection	±0.04% <sup>2)</sup> ±0.022% <sup>3)</sup>
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format	±0.04% <sup>2)</sup> ±0.022% <sup>3)</sup> Short-circuit proof
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format Voltage Current	lnternal enable relay for startup  ±0.04% ²) ±0.022% ³)  Short-circuit proof  INT 0x8000 - 0x7FFF / 1 LSB = 0x0001 = 305.176 μV
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format Voltage Current	lnternal enable relay for startup  ±0.04% ²) ±0.022% ³)  Short-circuit proof  INT 0x8000 - 0x7FFF / 1 LSB = 0x0001 = 305.176 μV
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format Voltage Current Load per channel	10.04% <sup>2)</sup> ±0.022% <sup>3)</sup> Short-circuit proof  INT 0x8000 - 0x7FFF / 1 LSB = 0x0001 = 305.176 μV INT 0x0000 - 0x7FFF / 1 LSB = 0x0001 = 610.352 nA
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format Voltage Current Load per channel Voltage	Internal enable relay for startup $ \frac{\pm 0.04\% \ ^2)}{\pm 0.022\% \ ^3)} $ Short-circuit proof $ \frac{1}{1} \text{INT } 0 \times 8000 - 0 \times 7 \text{FFF} / 1 \ \text{LSB} = 0 \times 0001 = 305.176 \ \mu\text{V} $ INT $0 \times 0000 - 0 \times 7 \text{FFF} / 1 \ \text{LSB} = 0 \times 0001 = 610.352 \ \text{nA} $ Max. $\pm 10 \ \text{mA}$ , load $\geq 1 \ \text{k}\Omega$
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format Voltage Current Load per channel Voltage Current	Internal enable relay for startup $ \frac{\pm 0.04\% \ ^2)}{\pm 0.022\% \ ^3)} $ $ \frac{\pm 0.022\% \ ^3)}{\text{Short-circuit proof}} $ INT $0 \times 8000 - 0 \times 7 \text{FFF} / 1 \text{ LSB} = 0 \times 0001 = 305.176 \ \mu\text{V} $ INT $0 \times 0000 - 0 \times 7 \text{FFF} / 1 \text{ LSB} = 0 \times 0001 = 610.352 \ nA $ $ \text{Max. } \pm 10 \ \text{mA, load} \geq 1 \ \text{k}\Omega $ $ \text{Max. load } 500 \ \Omega $
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format Voltage Current Load per channel Voltage Current Short-circuit proof	Internal enable relay for startup $ \frac{\pm 0.04\% \ ^2)}{\pm 0.022\% \ ^3)} $ Short-circuit proof $ 1111000000000000000000000000000000000$
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format Voltage Current Load per channel Voltage Current Short-circuit proof Output filter Error caused by load change	Internal enable relay for startup $ \frac{\pm 0.04\% \ ^2)}{\pm 0.022\% \ ^3)} $ Short-circuit proof $ \frac{1}{1} \text{INT } 0 \times 8000 - 0 \times 7 \text{FFF} / 1 \ \text{LSB} = 0 \times 0001 = 305.176 \ \mu\text{V} $ INT $0 \times 0000 - 0 \times 7 \text{FFF} / 1 \ \text{LSB} = 0 \times 0001 = 610.352 \ \text{nA} $ $ \frac{1}{1} \text{Max.} \ \pm 10 \ \text{mA, load} \ge 1 \ \text{k} \Omega $ $ \frac{1}{1} \text{Max.} \ \log 500 \ \Omega $ $ \frac{1}{1} \text{Current limiting } \pm 40 \ \text{mA} $ First-order low-pass filter / cutoff frequency $10 \ \text{kHz} $
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format Voltage Current Load per channel Voltage Current Short-circuit proof Output filter	Internal enable relay for startup $ \frac{\pm 0.04\% \ ^2)}{\pm 0.022\% \ ^3)} $ Short-circuit proof $ 1000000000000000000000000000000000000$
range Switch on/off behavior  Max. error <sup>1)</sup> Gain Offset Output protection Output format Voltage Current Load per channel Voltage Current Short-circuit proof Output filter Error caused by load change Voltage Voltage	Internal enable relay for startup $ \frac{\pm 0.04\% \ ^2)}{\pm 0.022\% \ ^3)} $ Short-circuit proof $ \frac{1}{1} \text{INT } 0 \times 8000 - 0 \times 7 \text{FFF} / 1 \ \text{LSB} = 0 \times 0001 = 305.176 \ \mu\text{V} $ INT $0 \times 0000 - 0 \times 7 \text{FFF} / 1 \ \text{LSB} = 0 \times 0001 = 610.352 \ \text{nA} $ $ \frac{1}{1} \text{Max.} \ \pm 10 \ \text{mA, load} \ge 1 \ \text{k} \Omega $ $ \frac{1}{1} \text{Max.} \ \log 500 \ \Omega $ $ \frac{1}{1} \text{Current limiting } \pm 40 \ \text{mA} $ First-order low-pass filter / cutoff frequency $10 \ \text{kHz} $

Table 2: X20AO4635 - Technical data

Order number	X20AO4635			
Signal				
0 to 20 mA				
Max. gain drift	±0.01%/°C <sup>2)</sup>			
Max. offset drift	±0.012%/°C <sup>3)</sup>			
±10 V				
Max. gain drift	±0.0025%/°C <sup>2)</sup>			
Max. offset drift	±0.001%/°C <sup>3)</sup>			
Electrical properties				
Electrical isolation	Channel isolated from bus			
	Channel not isolated from channel			
Operating conditions				
Mounting orientation				
Horizontal	Yes			
Vertical	Yes			
Installation elevation above sea level				
0 to 2000 m	No limitation			
>2000 m	Reduction of ambient temperature by 0.5°C per 100 m			
Degree of protection per EN 60529	IP20			
Ambient conditions				
Temperature				
Operation				
Horizontal mounting orientation	-25 to 55°C			
Vertical mounting orientation	-25 to 50°C			
Derating	See section "Derating".			
Storage	-40 to 85°C			
Transport	-40 to 85°C			
Relative humidity				
Operation	5 to 95%, non-condensing			
Storage	5 to 95%, non-condensing			
Transport	5 to 95%, non-condensing			
Mechanical properties				
Note	Order 1x terminal block X20TB12 separately.			
	Order 1x bus module X20BM11 separately.			
Pitch	12.5 <sup>+0.2</sup> mm			

Table 2: X20AO4635 - Technical data

- 1) At 25°C
- 2) Based on the current output value.
- 3) Based on the entire output range.

### 2.2 LED status indicators

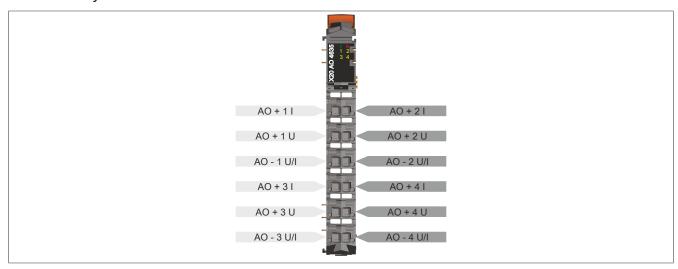
For a description of the various operating modes, see section "Additional information - Diagnostic LEDs" in the X20 system user's manual.

Figure	LED	Color	Status	Description
	r	Green	Off	No power to module
			Single flash	RESET mode
			Double flash	BOOT mode (during firmware update) <sup>1)</sup>
ig r e_			Blinking	PREOPERATIONAL mode
GE 97			On	RUN mode
(20 AO 4	е	Red	Off	No power to module or everything OK
			On	Error or reset status
	1 - 4 Oran	Orange	Off	Value = 0
-			On	Value ≠ 0

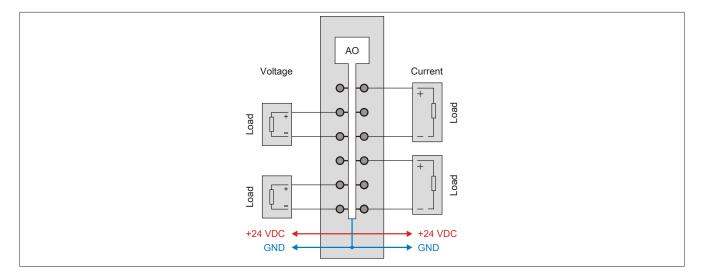
1) Depending on the configuration, a firmware update can take up to several minutes.

### 2.3 Pinout

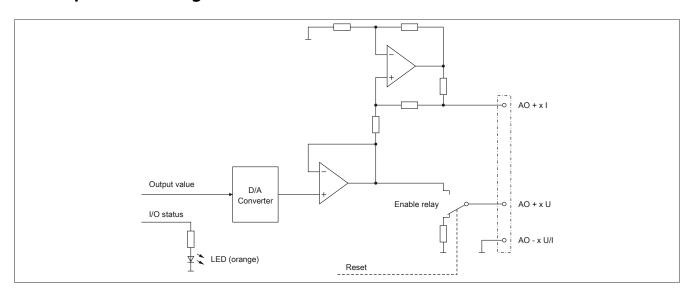
The individual channels can be configured for either current or voltage signals. The type of signal is also determined by the terminals used.



## 2.4 Connection example



## 2.5 Output circuit diagram



## 2.6 Derating

To ensure proper operation, the following items must be taken into consideration:

- The following derating listings must be taken into consideration
- For mixed operation with one current output, the average of both derating curves should be used
- For mixed operation with 2 or 3 current outputs, the derating for the current outputs should be used

### Horizontal installation

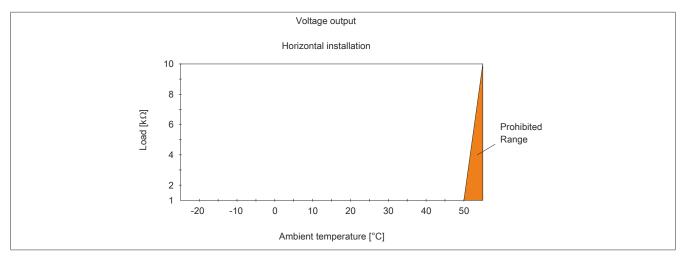
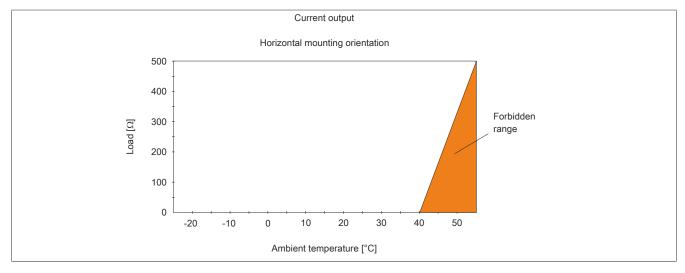


Figure 1: Derating the load with a voltage output and horizontal mounting



### **Technical description**

### Vertical installation

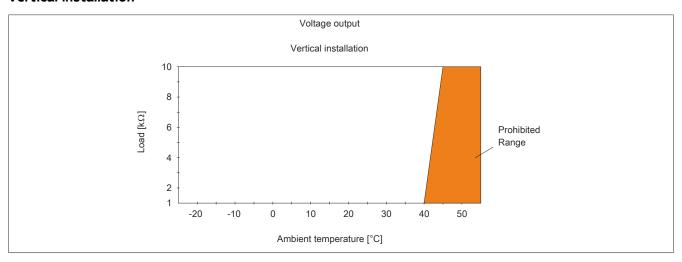
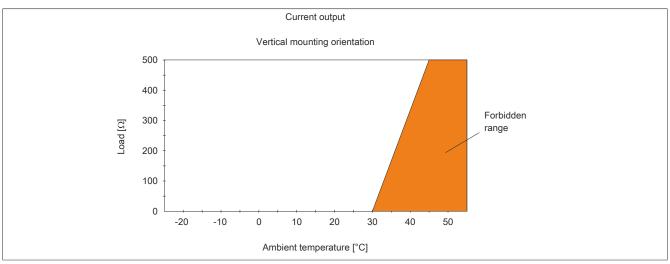


Figure 2: Derating the load with a voltage output and vertical mounting



## 3 Function description

## 3.1 Analog outputs

The module is equipped with 4 analog outputs.

The individual channels are designed for current and voltage signals. The differentiation is made by different terminal connections; because of different adjustment values for current and voltage, the output signal must be selected. The following output signals can be set:

- ±10 V voltage signal
- 0 to 20 mA current signal



### Information:

The register is described in "Setting the channel type" on page 12.

## 4 Commissioning

## 4.1 Using the module on the bus controller

Function model 254 "Bus controller" is used by default only by non-configurable bus controllers. All other bus controllers can use other registers and functions depending on the fieldbus used.

For detailed information, see section "Additional information - Using I/O modules on the bus controller" in the X20 user's manual (version 3.50 or later).

### 4.1.1 CAN I/O bus controller

The module occupies 1 analog logical slot on CAN I/O.

## **5 Register description**

## 5.1 General data points

In addition to the registers described in the register description, the module has additional general data points. These are not module-specific but contain general information such as serial number and hardware variant.

General data points are described in section "Additional information - General data points" in the X20 System user's manual.

### 5.2 Function model 0 - Standard

Register	Name	Data type	Read		Write	
			Cyclic	Non-cyclic	Cyclic	Non-cyclic
Configuration						
0	ConfigOutput01 (channel type) UINT •		•			
Communicati	on					
2	AnalogOutput01	INT			•	
4	AnalogOutput02	INT			•	
6	AnalogOutput03	INT			•	
8	AnalogOutput04	INT			•	

### 5.3 Function model 254 - Bus controller

Register	Offset <sup>1)</sup>	Name	Data type	Read		Write	
				Cyclic	Non-cyclic	Cyclic	Non-cyclic
Configuration							
0	-	ConfigOutput01 (channel type)	UINT				•
Communication	n						
2	0	AnalogOutput01	INT			•	
4	2	AnalogOutput02	INT			•	
6	4	AnalogOutput03	INT			•	
8	6	AnalogOutput04	INT			•	

<sup>1)</sup> The offset specifies the position of the register within the CAN object.

### 5.4 Analog outputs

The individual channels can be configured for either current or voltage signals. The type of signal is also determined by the terminals used.

### 5.4.1 Output values of the analog outputs

Name:

AnalogOutput01 to AnalogOutput04

The normalized output values are specified via these registers. After a permissible value is transferred, the module outputs the corresponding current or voltage.



### Information:

The value "0" disables the channel status LED.

Data type	Value	
INT	-32767 to 32767	Voltage
	0 to 32767	Current

### 5.4.2 Setting the channel type

Name:

ConfigOutput01

This register can be used to set the channel type of the outputs.

Data type	Values	Bus controller default setting
UINT	See the bit structure.	0

#### Bit structure:

Bit	Description	Value	Information
0 - 7	Reserved	0	
8	Channel 1	0	Voltage signal (bus controller default setting)
		1	Current signal
11	Channel 4	0	Voltage signal (bus controller default setting)
		1	Current signal
12 - 15	Reserved	0	

### 5.5 Minimum cycle time

The minimum cycle time specifies how far the bus cycle can be reduced without communication errors occurring. It is important to note that very fast cycles reduce the idle time available for handling monitoring, diagnostics and acyclic commands.

Minimum cycle time
200 μs

### 5.6 Minimum I/O update time

The minimum I/O update time specifies how far the bus cycle can be reduced so that an I/O update is performed in each cycle.

Minimum I/O update time
200 μs