

X20AI2222

Data sheet 1.30 (June 2025)



Publishing information

B&R Industrial Automation GmbH B&R Strasse 1 5142 Eggelsberg Austria

Telephone: +43 7748 6586-0

Fax: +43 7748 6586-26

office@br-automation.com

Disclaimer

All information in this document is current as of its creation. The contents of this document are subject to change without notice. B&R Industrial Automation GmbH assumes unlimited liability in particular for technical or editorial errors in this document only (i) in the event of gross negligence or (ii) for culpably inflicted personal injury. Beyond that, liability is excluded to the extent permitted by law. Liability in cases in which the law stipulates mandatory unlimited liability (such as product liability) remains unaffected. Liability for indirect damage, consequential damage, business interruption, loss of profit or loss of information and data is excluded, in particular for damage that is directly or indirectly attributable to the delivery, performance and use of this material.

B&R Industrial Automation GmbH notes that the software and hardware designations and brand names of the respective companies used in this document are subject to general trademark, brand or patent protection.

Hardware and software from third-party suppliers referenced in this document is subject exclusively to the respective terms of use of these third-party providers. B&R Industrial Automation GmbH assumes no liability in this regard. Any recommendations made by B&R Industrial Automation GmbH are not contractual content, but merely non-binding information for which no liability is assumed. When using hardware and software from third-party suppliers, the relevant user documentation of these third-party suppliers must additionally be consulted and, in particular, the safety guidelines and technical specifications contained therein must be observed. The compatibility of the products from B&R Industrial Automation GmbH described in this document with hardware and software from third-party suppliers is not contractual content unless this has been separately agreed in individual cases; in this respect, warranty for such compatibility is excluded in any case, and it is the sole responsibility of the customer to verify this compatibility in advance.

1328041535503-1.30

1 General information

1.1 Other applicable documents

For additional and supplementary information, see the following documents.

Other applicable documents

| Document name | Title |
|---------------|--------------------------|
| MAX20 | X20 System user's manual |

1.2 Order data

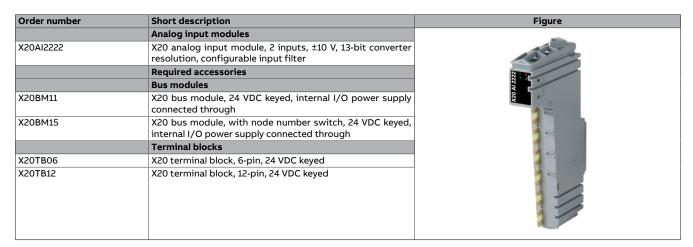


Table 1: X20AI2222 - Order data

1.3 Module description

The module is equipped with 2 inputs with 13-bit (including sign) digital converter resolution. Voltage signals in the range of ± 10 V can be recorded.

This module is designed for X20 6-pin terminal blocks. If needed (e.g. for logistical reasons), the 12-pin terminal block can also be used.

Functions:

- Input filter
- · Monitoring the input signal

Analog input filter

The module is equipped with a configurable input filter with input ramp limiting.

Monitoring the input signal

The input signal of the analog inputs is monitored against the upper and lower limit values as well as for open circuit.

2 Technical description

2.1 Technical data

| Order number | X20Al2222 |
|--|--|
| Short description | |
| I/O module | 2 analog inputs ±10 V |
| General information | . |
| B&R ID code | 0xCAB0 |
| Status indicators | I/O function per channel, operating state, module status |
| Diagnostics | 17 O Tunction per channel, operating state, module status |
| - | Vos. using LED status indicator and software |
| Module run/error | Yes, using LED status indicator and software |
| Inputs | Yes, using LED status indicator and software |
| Power consumption | |
| Bus | 0.01 W |
| Internal I/O | 0.8 W ¹⁾ |
| Additional power dissipation caused by actuators (resistive) [W] | <u>-</u> |
| Certifications | |
| CE | Yes |
| UKCA | Yes |
| ATEX | Zone 2, II 3G Ex nA nC IIA T5 Gc IP20, Ta (see X20 user's manual) FTZÚ 09 ATEX 0083X |
| UL HazLoc | cULus E115267 Industrial control equipment |
| DNV | Temperature: B (0 to 55°C) Humidity: B (up to 100%) Vibration: B (4 g) EMC: B (bridge and open deck) |
| CCS | Yes |
| LR | ENV1 |
| KR | Yes |
| ABS | Yes |
| BV | EC33B |
| BV | Temperature: 5 - 55°C Vibration: 4 g |
| Analogianute | EMC: Bridge and open deck |
| Analog inputs | 1401/ |
| Input | ±10 V |
| Input type | Differential input |
| Digital converter resolution | ±12-bit |
| Conversion time | 300 μs for all inputs |
| Output format | |
| Data type | INT |
| Voltage | 0x8001 - 0x7FFF / 1 LSB = 0x0008 = 2.441 mV |
| Input impedance in signal range | 20 ΜΩ |
| Input protection | Protection against wiring with supply voltage |
| Permissible input signal | Max. ±30 V |
| Output of digital value during overload | Configurable |
| Conversion procedure | SAR |
| Input filter | Third-order low-pass filter / Cutoff frequency 1 kHz |
| Max. error | Time of the passing of second requestry Entite |
| Gain | 0.08% 2) |
| Offset | 0.08% ⁵ |
| | |
| Max. gain drift | 0.006%/°C ²) |
| Max. offset drift | 0.002%/°C ³⁾ |
| Common-mode rejection | |
| DC | 70 dB |
| 50 Hz | 70 dB |
| Common-mode range | ±12 V |
| Crosstalk between channels | -70 dB |
| Nonlinearity | <0.025% ³⁾ |
| Insulation voltage between channel and bus | 500 V _{eff} |

Table 2: X20AI2222 - Technical data

| Order number | X20AI2222 |
|--|--|
| Electrical properties | |
| Electrical isolation | Channel isolated from bus |
| | Channel not isolated from channel |
| Operating conditions | |
| Mounting orientation | |
| Horizontal | Yes |
| Vertical | Yes |
| Installation elevation above sea level | |
| 0 to 2000 m | No limitation |
| >2000 m | Reduction of ambient temperature by 0.5°C per 100 m |
| Degree of protection per EN 60529 | IP20 |
| Ambient conditions | |
| Temperature | |
| Operation | |
| Horizontal mounting orientation | -25 to 60°C |
| Vertical mounting orientation | -25 to 50°C |
| Derating | - |
| Storage | -40 to 85°C |
| Transport | -40 to 85°C |
| Relative humidity | |
| Operation | 5 to 95%, non-condensing |
| Storage | 5 to 95%, non-condensing |
| Transport | 5 to 95%, non-condensing |
| Mechanical properties | |
| Note | Order 1x terminal block X20TB06 or X20TB12 separately. |
| | Order 1x bus module X20BM11 separately. |
| Pitch | 12.5 ^{+0.2} mm |

Table 2: X20AI2222 - Technical data

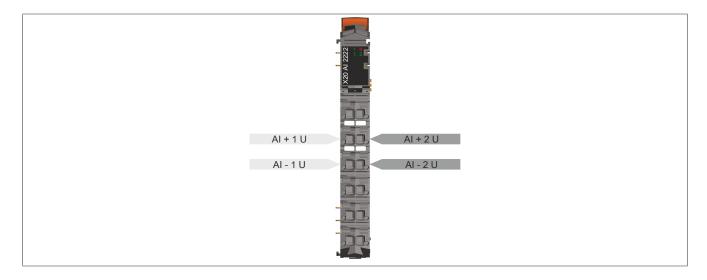
- 1) To reduce power dissipation, B&R recommends bridging unused inputs on the terminal.
- 2) Based on the current measured value.
- 3) Based on the 20 V measurement range.

2.2 LED status indicators

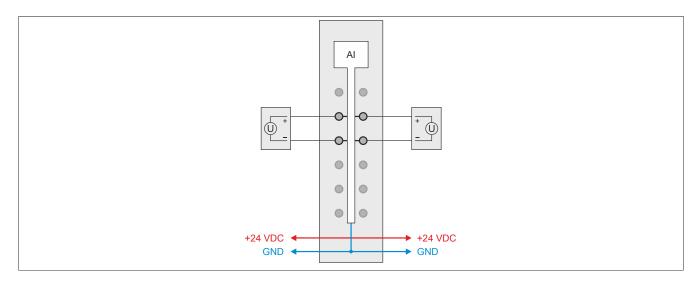
For a description of the various operating modes, see section "Additional information - Diagnostic LEDs" in the X20 system user's manual.

| Figure | LED | Color | Status | Description |
|--------|-----------------------------------|-------|----------------|--|
| | r | Green | Off | No power to module |
| | | | Single flash | RESET mode |
| | | | Blinking | PREOPERATIONAL mode |
| O C | | | On | RUN mode |
| 2222 | е | Red | Off | No power to module or everything OK |
| | | | On | Error or reset status |
| ₹ 5 | e + r Red on / Green single flash | | n single flash | Invalid firmware |
| X20 | 1 - 2 Green Off Blinkir | | Off | Open line or sensor is disconnected |
| * | | | Blinking | Input signal overflow or underflow |
| | | | On | Analog/digital converter running, value OK |

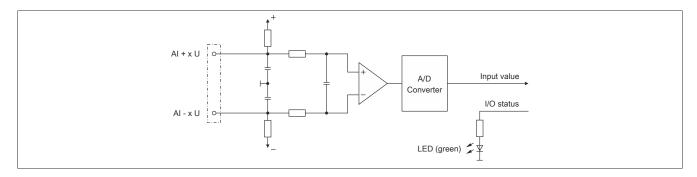
2.3 Pinout



2.4 Connection example



2.5 Input circuit diagram



3 Function description

3.1 Input filter

The module is equipped with a configurable input filter. The minimum cycle time must be >500 μ s. The filter function is disabled for shorter cycle times.

When the input filter is activated, the channels are sampled at millisecond intervals. The time offset between the channels is 200 μ s. The conversion takes place asynchronously to the network cycle.



Information:

The register is described in "Configuring the input filter" on page 13.

3.1.1 Input ramp limiting

Input ramp limiting can only be performed in conjunction with filtering. Input ramp limiting is performed before filtering.

The difference of the input value change is checked for exceeding the specified limit. In the event of overshoot, the tracked input value is equal to the old value ± the limit value.

Configurable limit values:

| Value | Limit value |
|-------|---|
| 0 | The input value is used without limitation. |
| 1 | 0x3FFF = 16383 |
| 2 | 0x1FFF = 8191 |
| 3 | 0x0FFF = 4095 |
| 4 | 0x07FF = 2047 |
| 5 | 0x03FF = 1023 |
| 6 | 0x01FF = 511 |
| 7 | 0x00FF = 255 |

Function description

Input ramp limiting is well suited for suppressing disturbances (spikes). The following examples show the functionality of input ramp limiting based on an input step and a disturbance.

Example 1

The input value jumps from 8000 to 17000. The diagram shows the tracked input value with the following settings:

Input ramp limiting = 4 = 0x07FF = 2047

Filter level = 2

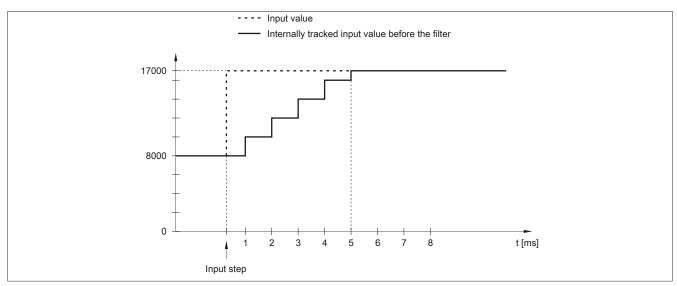


Figure 1: Tracked input value for input step

Example 2

A disturbance interferes with the input value. The diagram shows the tracked input value with the following settings:

Input ramp limiting = 4 = 0x07FF = 2047

Filter level = 2

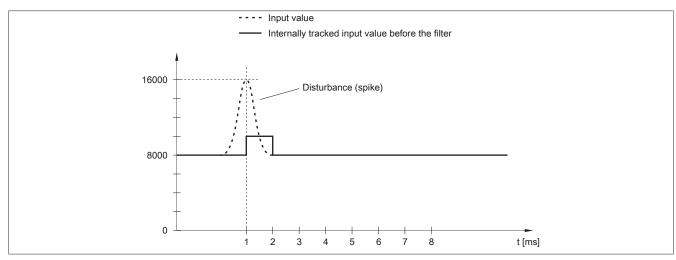


Figure 2: Tracked input value for disturbance

3.1.2 Filter level

A filter can be defined to prevent large input steps. This filter is used to bring the input value closer to the actual analog value over a period of several bus cycles.

Filtering takes place after any input ramp limiting has been carried out.

Formula for calculating the input value:

$$Value_{New} = Value_{Old} - \frac{Value_{Old}}{Filter level} + \frac{Input value}{Filter level}$$

Adjustable filter levels:

| Value | Filter level |
|-------|---------------------|
| 0 | Filter switched off |
| 1 | Filter level 2 |
| 2 | Filter level 4 |
| 3 | Filter level 8 |
| 4 | Filter level 16 |
| 5 | Filter level 32 |
| 6 | Filter level 64 |
| 7 | Filter level 128 |

The following examples show the functionality of the filter based on an input step and a disturbance.

Example 1

The input value jumps from 8000 to 16000. The diagram shows the calculated value with the following settings:

Input ramp limiting = 0

Filter level = 2 or 4

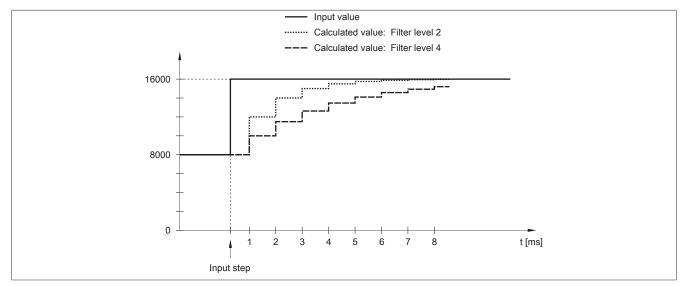


Figure 3: Calculated value during input step

Function description

Example 2

A disturbance interferes with the input value. The diagram shows the calculated value with the following settings:

Input ramp limiting = 0

Filter level = 2 or 4

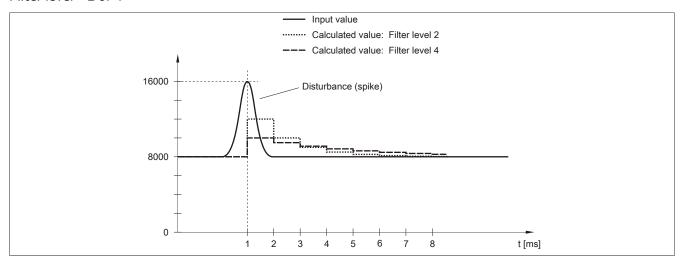


Figure 4: Calculated value during disturbance

3.2 Monitoring the input signal

The input signal is monitored against the upper and lower limit values as well as for open circuit.

| Limit value (default) | Voltage signal ±10 V | | | |
|---------------------------|-----------------------|-----------------|--|--|
| Upper maximum limit value | +10 V +32767 (0x7FFF) | | | |
| Lower minimum limit value | -10 V | -32767 (0x8001) | | |

Limiting the analog value

In addition to the status information, the analog value is fixed to the values listed below by default in an error state. The analog value is limited to the new values if the limit values were changed.

| Error state | Digital value on error (default values) |
|-----------------------------|---|
| Open circuit | +32767 (0x7FFF) |
| Upper limit value overshot | +32767 (0x7FFF) |
| Lower limit value undershot | -32767 (0x8001) |
| Invalid value | -32768 (0x8000) |



Information:

The register is described in "Input status" on page 14.

4 Commissioning

4.1 Using the module on the bus controller

Function model 254 "Bus controller" is used by default only by non-configurable bus controllers. All other bus controllers can use other registers and functions depending on the fieldbus used.

For detailed information, see section "Additional information - Using I/O modules on the bus controller" in the X20 user's manual (version 3.50 or later).

4.1.1 CAN I/O bus controller

The module occupies 1 analog logical slot on CAN I/O.

5 Register description

5.1 General data points

In addition to the registers described in the register description, the module has additional general data points. These are not module-specific but contain general information such as serial number and hardware variant.

General data points are described in section "Additional information - General data points" in the X20 System user's manual.

5.2 Function model 0 - Standard

| Register | Name | Data type | Read | | Write | | |
|---------------|------------------------------------|-----------|--------|------------|--------|------------|--|
| | | | Cyclic | Non-cyclic | Cyclic | Non-cyclic | |
| Analog signal | - Configuration | | | | | | |
| 16 | ConfigOutput01 (Input filter) | USINT | | | | • | |
| 20 | ConfigOutput03 (Lower limit value) | INT | | | | • | |
| 22 | ConfigOutput04 (Upper limit value) | INT | | | | • | |
| Analog signal | Analog signal - Communication | | | | | | |
| 0 | AnalogInput01 | INT | • | | | | |
| 2 | AnalogInput02 | INT | • | | | | |
| 30 | StatusInput01 | USINT | • | | | | |

5.3 Function model 254 - Bus controller

| Register | Offset ¹⁾ | Name | Data type | Read | | Write | |
|-------------------------------|----------------------|------------------------------------|-----------|--------|------------|--------|------------|
| | | | | Cyclic | Non-cyclic | Cyclic | Non-cyclic |
| Analog signal | - Configuratio | n | | | | | |
| 16 | - | ConfigOutput01 (Input filter) | USINT | | | | • |
| 20 | - | ConfigOutput03 (Lower limit value) | INT | | | | • |
| 22 | - | ConfigOutput04 (Upper limit value) | INT | | | | • |
| Analog signal - Communication | | | | | | | |
| 0 | 0 | AnalogInput01 | INT | • | | | |
| 2 | 2 | AnalogInput02 | INT | • | | | |
| 30 | - | StatusInput01 | USINT | | • | | |

The offset specifies the position of the register within the CAN object.

5.4 Analog signal - Configuration

5.4.1 Configuring the input filter

Name:

ConfigOutput01

The filter level and input ramp limiting of the input filter are set in this register.

| Data type | Values | Bus controller default setting |
|-----------|------------------------|--------------------------------|
| USINT | See the bit structure. | 0 |

Bit structure:

| Bit | Description | Value | Information |
|-------|-----------------------------|-------|--|
| 0 - 2 | Defines the filter level | 000 | Filter disabled (bus controller default setting) |
| | | 001 | Filter level 2 |
| | | 010 | Filter level 4 |
| | | 011 | Filter level 8 |
| | | 100 | Filter level 16 |
| | | 101 | Filter level 32 |
| | | 110 | Filter level 64 |
| | | 111 | Filter level 128 |
| 3 | Reserved | 0 | |
| 4 - 6 | Defines input ramp limiting | 000 | The input value is applied without limitation |
| | | | (bus controller default setting) |
| | | 001 | Limit value = 0x3FFF (16383) |
| | | 010 | Limit value = 0x1FFF (8191) |
| | | 011 | Limit value = 0x0FFF (4095) |
| | | 100 | Limit value = 0x07FF (2047) |
| | | 101 | Limit value = 0x03FF (1023) |
| | | 110 | Limit value = 0x01FF (511) |
| | | 111 | Limit value = 0x00FF (255) |
| 7 | Reserved | 0 | |

5.4.2 Lower limit value

Name:

ConfigOutput03

The lower limit value for analog values can be set in this register. If the analog value undershoots the limit value, it is frozen at this value and the corresponding error state bit is set.

| Data type | Values | Information |
|-----------|-----------------|--|
| INT | -32767 to 32767 | Bus controller default setting: -32767 |



Information:

The default value of -32767 corresponds to the minimum default value of -10 VDC. It is important to note that this setting applies to all channels!

5.4.3 Upper limit value

Name:

ConfigOutput04

The upper limit value for analog values can be set in this register. If the analog value overshoots the limit value, it is frozen at this value and the corresponding error state bit is set.

| Data type | Values | Information |
|-----------|-----------------|---------------------------------------|
| INT | -32767 to 32767 | Bus controller default setting: 32767 |



Information:

Default value 32767 corresponds to the maximum default value at +10 VDC. It is important to note that this setting applies to all channels!

5.5 Analog signal - Communication

5.5.1 Analog inputs

The input state is collected with a fixed offset to the network cycle and transferred in the same cycle.

5.5.2 Input values of analog inputs

Name:

AnalogInput01 to AnalogInput02

This register contains the analog input value.

| Data type | Values | Input signal: |
|-----------|-----------------|------------------------------|
| INT | -32768 to 32767 | Voltage signal -10 to 10 VDC |

5.5.3 Input status

Name:

StatusInput01

The module inputs are monitored in this register. A change in the monitoring status is actively issued as an error message and, in the event of an error, the analog value is fixed at defined values. For details, see "Monitoring the input signal" on page 10.

| Data type | Values |
|-----------|------------------------|
| USINT | See the bit structure. |

Bit structure:

| Bit | Description | Value | Information |
|-------|-------------|-------|----------------------------|
| 0 - 1 | Channel 1 | 00 | No error |
| | | 01 | Lower limit value exceeded |
| | | 10 | Upper limit value exceeded |
| | | 11 | Open line |
| 2 - 3 | Channel 2 | 00 | No error |
| | | 01 | Lower limit value exceeded |
| | | 10 | Upper limit value exceeded |
| | | 11 | Open line |
| 4 - 7 | Reserved | 0 | |

5.6 Minimum cycle time

The minimum cycle time specifies how far the bus cycle can be reduced without communication errors occurring. It is important to note that very fast cycles reduce the idle time available for handling monitoring, diagnostics and acyclic commands.

| | Minimum cycle time | |
|--------------------------|--------------------|--|
| Inputs without filtering | 100 μs | |
| Inputs with filtering | 500 μs | |

5.7 Minimum I/O update time

The minimum I/O update time specifies how far the bus cycle can be reduced so that an I/O update is performed in each cycle.

| Minimum I/O update time | |
|--------------------------|-----------------------|
| Inputs without filtering | 300 μs for all inputs |
| Inputs with filtering | 1 ms |