

X20D02649

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B&R Industrial Automation GmbH B&R Strasse 1 5142 Eggelsberg Austria

Telephone: +43 7748 6586-0

Fax: +43 7748 6586-26

office@br-automation.com

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Version history

B&R makes every effort to keep documents as current as possible. The most current versions are available for download on the B&R website (www.br-automation.com).

1 General information

1.1 Other applicable documents

For additional and supplementary information, see the following documents.

Other applicable documents

Document name	Title
MAX20	X20 System user's manual
MAEMV	Installations / EMV guide

1.2 Order data

Table 1: X20DO2649 - Order data

1.3 Module description

The module is equipped with 2 relay outputs with changeover contacts for 240 VAC / 30 VDC. The outputs are single-channel isolated.

Functions:

· Digital outputs



Danger!

Risk of electric shock!

The terminal block is only permitted to conduct voltage when it is connected. It is not permitted to be disconnected or connected while voltage is applied or have voltage applied to it while it is removed under any circumstances!

This module is not permitted to be the last module connected on the X2X Link network. At least one subsequent X2OZF dummy module must provide protection against contact.



Danger!

The voltage classes on the terminal block are not permitted to be mixed! Only operation with the mains voltage (e.g. 230 VAC) OR with safety extra-low voltage (e.g. 24 VDC SELV) is permitted.

X20DO2649 Data sheet V 3.20 3

2 Technical description

2.1 Technical data

Order number	X20DO2649
Short description	
I/O module	2 digital outputs 30 VDC / 240 VAC, outputs single-channel isolated
General information	
B&R ID code	0x20DA
Status indicators	I/O function per channel, operating state, module status
Diagnostics	
Module run/error	Yes, using LED status indicator and software
Outputs	Yes, using LED status indicator
Power consumption	
Bus	0.45 W
Internal I/O	•
Additional power dissipation caused by actuators (resistive) [W] ¹⁾	+2.5
Certifications	
CE	Yes
UKCA	Yes
ATEX	Zone 2, II 3G Ex nA nC IIA T5 Gc IP20, Ta (see X20 user's manual) FTZÚ 09 ATEX 0083X
UL	cULus E115267
	Industrial control equipment
HazLoc	cCSAus 244665 Process control equipment for hazardous locations Class I, Division 2, Groups ABCD, T5
DNV	Temperature: B (0 to 55°C) Humidity: B (up to 100%) Vibration: B (4 g) EMC: B (bridge and open deck)
CCS	Yes
LR	ENV1
KR	Yes
ABS	Yes
BV	EC33B Temperature: 5 - 55°C Vibration: 4 g EMC: Bridge and open deck
KC	Yes
Digital outputs	
Variant	Relay / Changeover contact Channels are single-channel isolated.
Nominal voltage	30 VDC / 240 VAC
Max. voltage	264 VAC
Switching voltage	Max. 110 VDC / 264 VAC
Rated frequency	DC / 45 to 63 Hz
Nominal output current	5 A at 30 VDC / 5 A at 240 VAC
Total nominal current	10 A at 30 VDC / 10 A at 240 VAC
Actuator power supply	External
Inrush current	Max. 6 A (per channel)
Contact resistance	50 mΩ
Switching delay	
0 → 1	≤10 ms
1 → 0	≤10 ms
Insulation voltages	
Channel - Bus	Tested at 4000 VAC
Channel - Channel	Tested at 1000 VAC
Service life	
Electrical 2)	Min. 60×10^3 ops. (NC) at 6 A Min. 30×30^3 ops. (NO) at 6 A
Mechanical	Min. 10 x 10 ⁶ ops.
Switching capacity	·
Minimum	10 mA / 5 VDC
Maximum	180 W / 1500 VA

Table 2: X20DO2649 - Technical data

4 X20DO2649 Data sheet V 3.20

Order number	X20DO2649	
Protective circuit		
Internal	None	
External		
AC	RC combination or VDR	
DC	Inverse diode, RC combination or VDR	
Electrical properties		
Electrical isolation	Channel isolated from channel, bus and I/O power supply	
Operating conditions		
Mounting orientation		
Horizontal	Yes	
Vertical	Yes	
Installation elevation above sea level		
0 to 2000 m	No limitation	
>2000 m	Not permitted	
Degree of protection per EN 60529	IP20	
Ambient conditions		
Temperature		
Operation		
Horizontal mounting orientation	-25 to 60°C	
Vertical mounting orientation	-25 to 50°C	
Derating	See section "Derating".	
Storage	-40 to 85°C	
Transport	-40 to 85°C	
Relative humidity		
Operation	5 to 95%, non-condensing	
Storage	5 to 95%, non-condensing	
Transport	5 to 95%, non-condensing	
Mechanical properties		
Note	Order 1x terminal block X20TB12 separately.	
	Order 1x bus module X20BM11 separately.	
Pitch	12.5 ^{+0.2} mm	

Table 2: X20DO2649 - Technical data

- 1) Number of outputs x Contact resistance x Nominal output current². For a calculation example, see section "Mechanical and electrical configuration" in the X20 system user's manual.
- 2) With resistive load. See also section "Electrical service life".

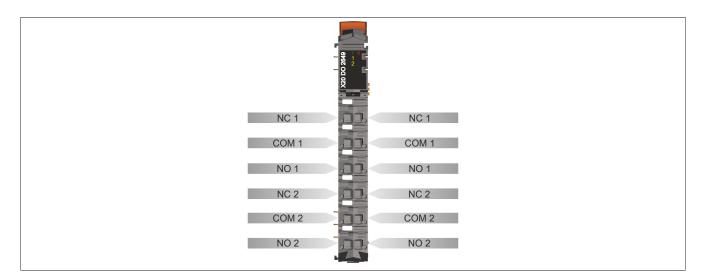
2.2 Status LEDs

For a description of the various operating modes, see section "Additional information - Diagnostic LEDs" in the X20 System user's manual.

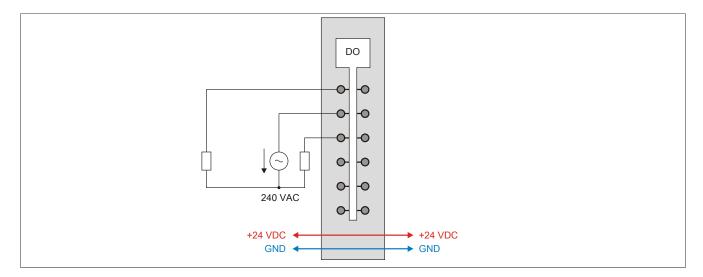
Figure	LED	Color	Status	Description		
	r Green Off Module supply not connected		Module supply not connected			
			Single flash	RESET mode		
			Blinking	PREOPERATIONAL mode		
o re			On	RUN mode		
7 1 2 P	е	Red	Off	Module supply not connected or everything OK		
8 6			On	Error or reset status		
	e + r	Red on / Greer	n single flash	Invalid firmware		
(20	1-2	Orange		Output status of the corresponding digital output		
^						
THE LAND CO.						

X20DO2649 Data sheet V 3.20

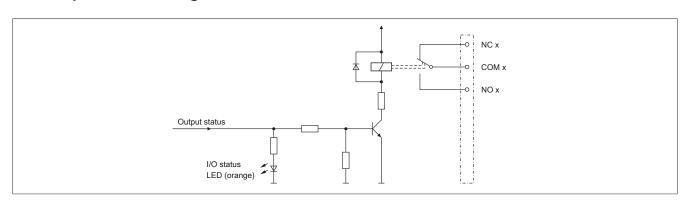
2.3 Pinout



2.4 Connection example

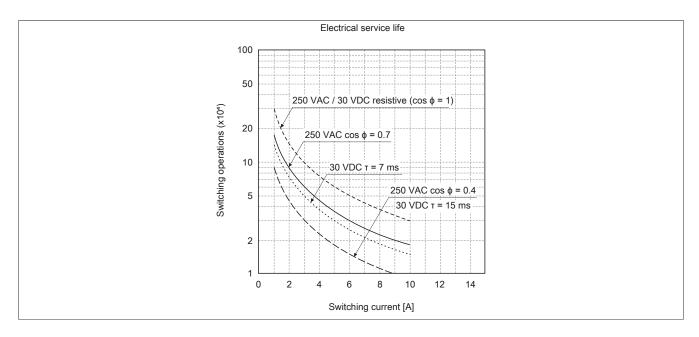


2.5 Output circuit diagram



6 X20D02649 Data sheet V 3.20

2.6 Electrical service life



2.7 Derating

There is no derating when operated below 55°C.

When operating above 55°C, the maximum current per channel is reduced to 4 A and the maximum summation current to 8 A!

X20DO2649 Data sheet V 3.20 7

3 Function description

3.1 Digital outputs

The module is equipped with 2 relay outputs with changeover contacts.

The output state is transferred to the output channels with a fixed offset ($<60 \,\mu s$) in relation to the network cycle (SyncOut).

Packed outputs (only function model 0 - Standard)

Setting "Packed outputs" in the Automation Studio I/O configuration can be used to determine whether all bits of the register should be applied as individual data points in the Automation Studio I/O mapping ("DigitalOutput01 to DigitalOutputxx") or whether the register should be displayed as a single USINT data point ("DigitalOutput").



8

Information:

The register is described in "Switching state of digital outputs 1 to 2" on page 10.

X20D02649 Data sheet V 3.20

4 Commissioning

4.1 Using the module on the bus controller

Function model 254 "Bus controller" is used by default only by non-configurable bus controllers. All other bus controllers can use other registers and functions depending on the fieldbus used.

For detailed information, see section "Additional information - Using I/O modules on the bus controller" in the X20 user's manual (version 3.50 or later).

4.1.1 CAN I/O bus controller

The module occupies 1 digital logical slot on CAN I/O.

X20D02649 Data sheet V 3.20 9

5 Register description

5.1 General data points

In addition to the registers described in the register description, the module has additional general data points. These are not module-specific but contain general information such as serial number and hardware variant.

General data points are described in section "Additional information - General data points" in the X20 System user's manual.

5.2 Function model 0 - Standard

Register	Fixed offset	Name	Data type	Read		Write	
				Cyclic	Acyclic	Cyclic	Acyclic
2	0	DigitalOutput	USINT			•	
		DigitalOutput01	Bit 0				
		DigitalOutput02	Bit 1				

Fixed modules require their data points to be in a specific order in the X2X frame. Cyclic access occurs according to a predefined offset, not based on the register address.

Acyclic access continues to be based on the register numbers.

5.3 Function model 254 - Bus Controller

Register	Offset ¹⁾	Name	Data type	Read		Write		
				Cyclic	Acyclic	Cyclic	Acyclic	
2	0	Switching state of digital outputs 1 to 2	USINT			•		
		DigitalOutput01	Bit 0					
		DigitalOutput02	Bit 1					

¹⁾ The offset specifies where the register is within the CAN object.

5.4 Digital outputs

5.4.1 Switching state of digital outputs 1 to 2

Name:

DigitalOutput

DigitalOutput01 to DigitalOutput02

This register is used to store the switching state of digital outputs 1 to 2.

Data type	Values	Information ¹⁾
USINT	0 to 3	Packed outputs = On
		Data point: "DigitalOutput"
	See the bit structure.	Packed outputs = Off or function model ≠ 0 - Standard.
		Data points: "DigitalOutput01" to "DigitalOutput02"

See "Digital outputs" on page 8.

Bit structure:

Bit	Name	Value	Information
0	DigitalOutput01	0	Digital output 01 reset
		1	Digital output 01 set
1	DigitalOutput02	0	Digital output 02 reset
		1	Digital output 02 set

10 X20D02649 Data sheet V 3.20

5.5 Minimum cycle time

The minimum cycle time specifies how far the bus cycle can be reduced without communication errors occurring. It is important to note that very fast cycles reduce the idle time available for handling monitoring, diagnostics and acyclic commands.

Minimum cycle time
100 μs

5.6 Minimum I/O update time

The minimum I/O update time specifies how far the bus cycle can be reduced so that an I/O update is performed in each cycle.

Minimum I/O update time
Favorite the minimum grade time
Equal to the minimum cycle time

X20DO2649 Data sheet V 3.20