### **Product datasheet** Characteristics

### ATV12H018M2

variable speed drive ATV12 - 0.18kW - 0.25hp -200..240V - 1ph



#### Main

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Main		
Range of product	Altivar 12	
Product or component type	Variable speed drive	
Product destination	Asynchronous motors	
Product specific application	Simple machine	
Assembly style	On base plate	
Component name	ATV12	
Quantity per set	Set of 1	
EMC filter	Integrated	
Built-in fan	Without	
Network number of phases	Single phase	
[Us] rated supply voltage	200240 V (- 1510 %)	
Motor power kW	0.18 kW	
Motor power hp	0.25 hp	
Communication port protocol	Modbus	
Line current	2.8 A at 240 V 3.4 A at 200 V	
Speed range	120	
Transient overtorque	150170 % of nominal motor torque depending on drive rating and type of motor	
Asynchronous motor control profile	Quadratic voltage/frequency ratio Voltage/Frequency ratio (V/f) Sensorless flux vector control	
IP degree of protection	IP20 without blanking plate on upper part	
Noise level	0 dB	
Complementary		
Supply frequency	50/60 Hz (+/- 5 %)	
Type of connector	1 RJ45 for Modbus on front face	
Physical interface	2-wire RS 485 for Modbus	
0+20 2016		

#### Supply frequency 50/60 Hz (+/- 5 %) Type of connector 1 RJ45 for Modbus on front face Physical interface 2-wire RS 485 for Modbus



Transmission frame	RTU for Modbus
Transmission rate	4800 bit/s 38400 bit/s 19200 bit/s
	9600 bit/s
Number of addresses	1247 for Modbus
Communication service	Read/Write multiple registers (23), messaging: 4/4 words maximum Write multiple registers (16), messaging: 27 words maximum Read device identification (43) Write single register (06), messaging: 29 words maximum Read holding registers (03), messaging: 29 words maximum
Prospective line Isc	<= 1 kA
Continuous output current	1.4 A at 4 kHz
Maximum transient current	2.1 A for 60 s
Speed drive output frequency	0.5400 Hz
Nominal switching frequency	4 kHz
Switching frequency	416 kHz with derating factor 216 kHz adjustable
Braking torque	Up to 70 % of nominal motor torque without braking resistor
Motor slip compensation	Preset in factory Adjustable
Output voltage	200240 V single phase
Electrical connection	L1, L2, L3, U, V, W, PA, PC terminal 3.5 mm <sup>2</sup> (AWG 12)
Tightening torque	0.8 N.m
Insulation	Electrical between power and control
Supply	Internal supply for logic inputs 24 V DC, voltage limits 20.428.8 V, 100 mA for overload and short- circuit protection Internal supply for reference potentiometer 5 V DC, voltage limits 4.755.25 V, 10 mA for overload and short-circuit protection
Analogue input number	1
Analogue input type	Al1 configurable current 020 mA, impedance 250 Ohm Al1 configurable voltage 05 V, impedance 30 kOhm Al1 configurable voltage 010 V, impedance 30 kOhm
Discrete input number	4
Discrete input type	(LI1LI4) programmable, 24 V, voltage limits 1830 V
Discrete input logic	Negative logic (sink), > 16 V (state 0), < 10 V (state 1), input impedance 3.5 kOhm Positive logic (source), 0< 5 V (state 0), > 11 V (state 1)
Sampling duration	< 10 ms for analogue input < 20 ms, tolerance +/- 1 ms for logic input
Linearity error	+/- 0.3 % of maximum value for analogue input
Analogue output number	1
Analogue output type	<ul> <li>(AO1) software-configurable current, analogue output range 020 mA, output impedance 800 Ohm, analogue output resolution 8 bits</li> <li>(AO1) software-configurable voltage, analogue output range 010 V, output impedance 470 Ohm, analogue output resolution 8 bits</li> </ul>
Discrete output number	2
Discrete output type	(R1A, R1B, R1C) protected relay output 1 C/O (LO+, LO-) logic output
Minimum switching current	5 mA at 24 V DC for logic relay
Maximum switching current	3 A at 250 V AC resistive load cos phi = $1 L/R = 0$ ms for logic relay 2 A at 250 V AC inductive load cos phi = $0.4 L/R = 7$ ms for logic relay 4 A at 30 V DC resistive load cos phi = $1 L/R = 0$ ms for logic relay 2 A at 30 V DC inductive load cos phi = $0.4 L/R = 7$ ms for logic relay
Acceleration and deceleration ramps	Linear from 0 to 999.9 s S U
Braking to standstill	By DC injection, 0.130 s
Protection type	Line supply overvoltage Line supply undervoltage Against input phase loss in three-phase Overcurrent between output phases and earth Thermal motor protection via the drive by continuous calculation of I <sup>2</sup> t



	Short-circuit between motor phases Overheating protection	
Frequency resolution	Display unit 0.1 Hz Analog input converter A/D, 10 bits	
Time constant	20 ms, tolerance +/- 1 ms for reference change	
Marking	CE	
Operating position	Vertical +/- 10 degree	
Height	143 mm	
Width	72 mm	
Depth	102.2 mm	
Product weight	0.7 kg	
Functionality	Basic	
Specific application	Centrifugal pumps and fans Other applications	
Environment		
Electromagnetic compatibility	Electrostatic discharge immunity test (level 3) conforming to EN/IEC 61000-4-2 Surge immunity test (level 3) conforming to EN/IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to EN/IEC 61000-4-11 Electrical fast transient/burst immunity test (level 4) conforming to EN/IEC 61000-4-4 Immunity to conducted disturbances (level 3) conforming to EN/IEC 61000-4-6 Radiated radio-frequency electromagnetic field immunity test (level 3) conforming to EN/IEC 61000-4-3	
Electromagnetic emission	Conducted emissions with additional EMC filter, class: environment 1 category C2 conforming to EN/ IEC 61800-3 - test level: 412 kHz, <= 50 m shielded motor cable Conducted emissions with additional EMC filter, class: environment 1 category C1 conforming to EN/ IEC 61800-3 - test level: 412 kHz, <= 20 m shielded motor cable Conducted emissions with additional EMC filter, class: environment 2 category C3 conforming to EN/ IEC 61800-3 - test level: 412 kHz, <= 50 m shielded motor cable Conducted emissions with integrated EMC filter, class: environment 1 category C2 conforming to EN/ IEC 61800-3 - test level: 2, 4 and 16 kHz, <= 10 m shielded motor cable Radiated emissions, class: environment 1 category C2 conforming to EN/IEC 61800-3 - test level: 2, 4 and 16 kHz, <= 10 m shielded motor cable Conducted emissions, class: environment 1 category C2 conforming to EN/IEC 61800-3 - test level: 216 kHz shielded motor cable Conducted emissions with integrated EMC filter, class: environment 1 category C1 conforming to EN/IEC 61800-3 - test level: 2, 4, 8, 12 and 16 kHz, <= 5 m shielded motor cable Conducted emissions with integrated EMC filter, class: environment 1 category C2 conforming to EN/IEC 61800-3 - test level: 2, 4, 8, 12 and 16 kHz, <= 5 m shielded motor cable Conducted emissions with integrated EMC filter, class: environment 1 category C2 conforming to EN/IEC 61800-3 - test level: 2,12 kHz, <= 5 m shielded motor cable	
Product certifications	NOM UL GOST C-Tick CSA	
Vibration resistance	1 gn (f = 13200 Hz) conforming to EN/IEC 60068-2-6 1.5 mm peak to peak (f = 313 Hz) drive unmounted on symmetrical DIN rail conforming to EN/IEC 60068-2-6	
Shock resistance	15 gn for 11 ms conforming to EN/IEC 60068-2-27	
Relative humidity	595 % without dripping water conforming to IEC 60068-2-3 595 % without condensation conforming to IEC 60068-2-3	
Ambient air temperature for storage	-2570 °C	
Ambient air temperature for operation	4060 °C with current derating 2.2 % per °C -1040 °C with protective cover from the top of the drive removed	
Operating altitude	<= 1000 m without derating > 10002000 m with current derating 1 % per 100 m	

#### Offer Sustainability

Sustainable offer status	Green Premium product
RoHS (date code: YYWW)	Compliant - since 0901 - Schneider Electric declaration of conformity
	Schneider Electric declaration of conformity
REACh	Reference contains SVHC above the threshold - Go to CaP for more details
	🚰 Go to CaP for more details
Product environmental profile	Available



	Product environmental
Product end of life instructions	Available

18 months

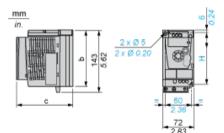
#### Contractual warranty

Warranty period

Schneider Electric

### Dimensions

#### Drive without EMC Conformity Kit



#### Dimensions in mm

b	c	Н
142	102.2	131
Dimensions in in.		

b	c	Н
5.59	4.02	5.16

#### Drive with EMC Conformity Kit

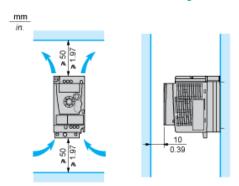
#### Dimensions in mm

c1	
34	
Dimensions in in.	
c1	
1.34	

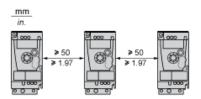


### Mounting Recommendations

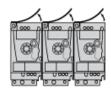
#### Clearance for Vertical Mounting



### Mounting Type A

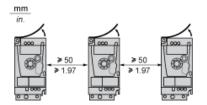


#### Mounting Type B



Remove the protective cover from the top of the drive.

#### Mounting Type C



Remove the protective cover from the top of the drive.

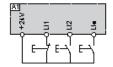


#### **Recommended Schemes**

#### 2-Wire Control for Logic I/O with Internal Power Supply

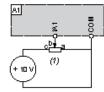
- LI1: Forward
- LI.: Reverse
- A1: Drive

#### 3-Wire Control for Logic I/O with Internal Power Supply



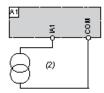
- LI1: Stop
- LI2: Forward
- LI.: Reverse A1: Drive

#### Analog Input Configured for Voltage with Internal Power Supply



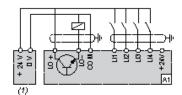
(1) 2.2 kΩ...10 kΩ reference potentiometer A1: Drive

#### Analog Input Configured for Current with Internal Power Supply



0-20 mA 4-20 mA supply (2) A1: Drive

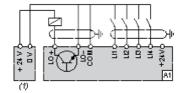
#### Connected as Positive Logic (Source) with External 24 vdc Supply



(1) 24 vdc supply A1: Drive



### Connected as Negative Logic (Sink) with External 24 vdc supply



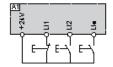
(1) 24 vdc supply A1 : Drive

#### **Recommended Schemes**

#### 2-Wire Control for Logic I/O with Internal Power Supply

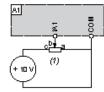
- LI1: Forward
- LI.: Reverse
- A1: Drive

#### 3-Wire Control for Logic I/O with Internal Power Supply



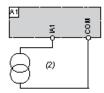
- LI1: Stop
- LI2: Forward
- LI.: Reverse A1: Drive

#### Analog Input Configured for Voltage with Internal Power Supply



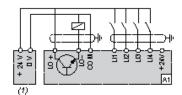
(1) 2.2 kΩ...10 kΩ reference potentiometer A1: Drive

#### Analog Input Configured for Current with Internal Power Supply



0-20 mA 4-20 mA supply (2) A1: Drive

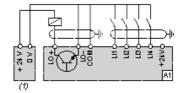
#### Connected as Positive Logic (Source) with External 24 vdc Supply



(1) 24 vdc supply A1: Drive



### Connected as Negative Logic (Sink) with External 24 vdc supply



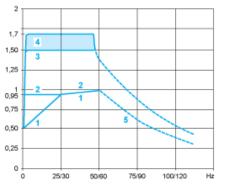
(1) 24 vdc supply A1 : Drive

**Product datasheet** 

### ATV12H018M2

**Performance Curves** 

#### **Torque Curves**



- 1: Self-cooled motor: continuous useful torque (1)
- 2: Force-cooled motor: continuous useful torque
- 3: Transient overtorque for 60 s
- 4: Transient overtorque for 2 s
- 5: Torque in overspeed at constant power (2)
- For power ratings ≤ 250 W, derating is 20% instead of 50% at very low frequencies. (1)
- (2) The nominal motor frequency and the maximum output frequency can be adjusted from 0.5 to 400 Hz. The mechanical overspeed capability of the selec

